

Modbus Configuration CS8C / CS9

Technical documentation

White paper



A "readme.pdf" document may be delivered on the robot's DVD. It contains the documentation addenda and errata.

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History

| Revision | Modification | Date (yyyy-mm-dd) | By |
|----------|--|----------------------|----------|
| A | Initial White Paper release (corresponding to the revision 2 of the previous document Modbus Configuration) | 2020-05-29 | A.JAFFRE |
| B | | | |
| C | | | |
| | | | |

Version

That document has been tested with:

- SRC : s8.10.2
- Safety : 1.003 / SafePMT 3.0.0.28
- SYCON.net : 1.500.180608.23664 (SRS 2019.7.1)

Keyword

Fieldbus, Modbus, Configuration, Client, Server, Input, Output, CS9, CS8C, Word, Bit, Address, Registers

1 Preliminary

DANGER



Instructions drawing the reader's attention to the risks of accidents that could lead to serious bodily harm if the steps shown are not complied with. In general, this type of indication describes the potential danger, its possible effects and the necessary steps to reduce the danger.

It is essential to comply with the instructions to ensure personal safety..

SAFETY



Instructions drawing the reader's attention that its responsibility is engaged if the steps shown are not complied with.

It is essential to comply with the instructions to maintain the robot safety level.

Caution



Instructions directing the reader's attention to the risks of material damage or failure if the steps shown are not complied with. It is essential to comply with these instructions to ensure equipment reliability and performance levels.

ELECTRICAL risk



Instructions drawing the reader's attention to the risks of electrical shock.

It is essential to comply with the instructions to ensure personal safety..

Information

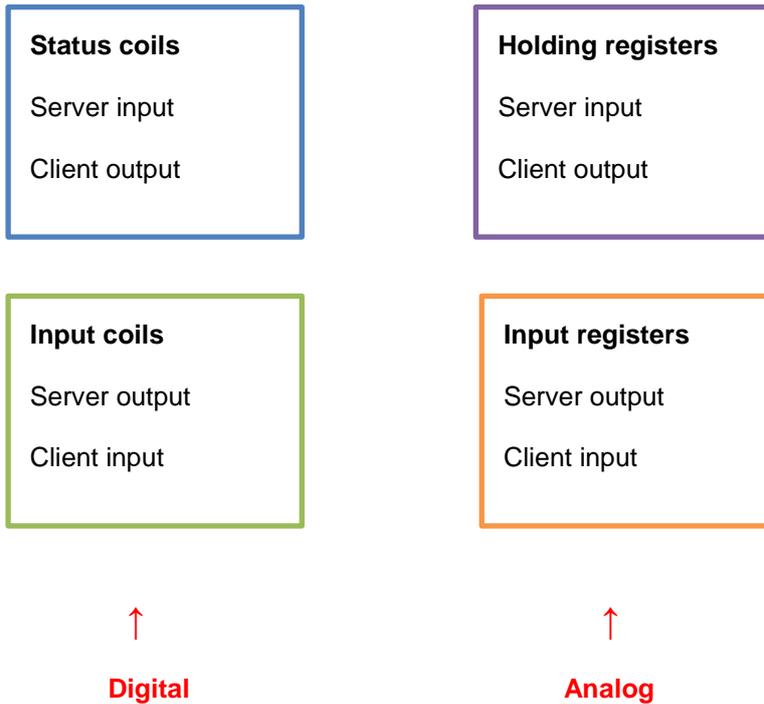


Supplies further information, or underlines a point or an important procedure. This information must be memorized to make it easier to apply and ensure correct sequencing of the operations described.

2 Modbus simplified

Below explanation are very simplified.

In Modbus, we have 4 databases, depending on element type:



| Modbus name | Prefix | Address (max) | For a server (slave) | For a client (master) | FC |
|-------------------------|----------|----------------------------------|----------------------|-----------------------|--------------|
| Status coil | 0 | 0 00001 to 0 65536 | Input (R) | Output (R/W) | 1, 5, 15 |
| Input coil | 1 | 1 00001 to 1 65536 | Output (R/W) | Input (R) | 2 |
| Input register | 3 | 3 00001 to 3 65536 | Output (R/W) | Input (R) | 4 |
| Holding register | 4 | 4 00001 to 4 65536 | Input (R) | Output (R/W) | 3, 6, 16, 23 |

Sometimes, address evolve from 0 to 65535 instead of 1 to 65536.

Coils are single bits (0 or 1), digital inputs/outputs while registers are 16 bits unsigned integer (0 to 65535), analog inputs/outputs.

FC are the function codes used to query the server.

Each equipment can choose what he wants to support and in which quantity. This is where the fun start.

3 Exchange table

Before starting to make a modbus configuration, you have to write your exchange table in order to know the mapping you need between server input/output and client input/output.

In order clarify; we will always speak the same way regarding input and output.

In the following explanation, we will always express them from the master point of view (client in Modbus terminology)

Ideally, if equipment's are organized the same way, it looks like that:

| Digital input | | | | | | |
|-----------------|-----|------------|----------------|---------|-----|------|
| Client (master) | | | Server (slave) | | | |
| Word | Bit | Input name | Output name | Address | Bit | Word |
| 1 | 1 | DI_01 | DO_01 | 100001 | 1 | 1 |
| | 2 | DI_02 | DO_02 | 100002 | 2 | |
| | 3 | DI_03 | DO_03 | 100003 | 3 | |
| | 4 | DI_04 | DO_04 | 100004 | 4 | |
| | 5 | DI_05 | DO_05 | 100005 | 5 | |
| | 6 | DI_06 | DO_06 | 100006 | 6 | |
| | 7 | DI_07 | DO_07 | 100007 | 7 | |
| | 8 | DI_08 | DO_08 | 100008 | 8 | |
| | 9 | DI_09 | DO_09 | 100009 | 9 | |
| | 10 | DI_10 | DO_10 | 100010 | 10 | |
| | 11 | DI_11 | DO_11 | 100011 | 11 | |
| | 12 | DI_12 | DO_12 | 100012 | 12 | |
| | 13 | DI_13 | DO_13 | 100013 | 13 | |
| | 14 | DI_14 | DO_14 | 100014 | 14 | |
| | 15 | DI_15 | DO_15 | 100015 | 15 | |
| | 16 | DI_16 | DO_16 | 100016 | 16 | |
| 2 | 17 | DI_17 | DO_17 | 100017 | 17 | 2 |
| | 18 | DI_18 | DO_18 | 100018 | 18 | |
| | 19 | DI_19 | DO_19 | 100019 | 19 | |
| | 20 | DI_20 | DO_20 | 100020 | 20 | |
| | 21 | DI_21 | DO_21 | 100021 | 21 | |
| | 22 | DI_22 | DO_22 | 100022 | 22 | |
| | 23 | DI_23 | DO_23 | 100023 | 23 | |
| | 24 | DI_24 | DO_24 | 100024 | 24 | |
| | 25 | DI_25 | DO_25 | 100025 | 25 | |
| | 26 | DI_26 | DO_26 | 100026 | 26 | |
| | 27 | DI_27 | DO_27 | 100027 | 27 | |
| | 28 | DI_28 | DO_28 | 100028 | 28 | |
| | 29 | DI_29 | DO_29 | 100029 | 29 | |
| | 30 | DI_30 | DO_30 | 100030 | 30 | |
| | 31 | DI_31 | DO_31 | 100031 | 31 | |
| | 32 | DI_32 | DO_32 | 100032 | 32 | |

| Digital output | | | | | | |
|-----------------|-----|-------------|----------------|---------|-----|------|
| Client (master) | | | Server (slave) | | | |
| Word | Bit | Output name | Input name | Address | Bit | Word |
| 1 | 1 | DO_01 | DI_01 | 000001 | 1 | 1 |
| | 2 | DO_02 | DI_02 | 000002 | 2 | |
| | 3 | DO_03 | DI_03 | 000003 | 3 | |
| | 4 | DO_04 | DI_04 | 000004 | 4 | |
| | 5 | DO_05 | DI_05 | 000005 | 5 | |
| | 6 | DO_06 | DI_06 | 000006 | 6 | |
| | 7 | DO_07 | DI_07 | 000007 | 7 | |
| | 8 | DO_08 | DI_08 | 000008 | 8 | |
| | 9 | DO_09 | DI_09 | 000009 | 9 | |
| | 10 | DO_10 | DI_10 | 000010 | 10 | |
| | 11 | DO_11 | DI_11 | 000011 | 11 | |
| | 12 | DO_12 | DI_12 | 000012 | 12 | |
| | 13 | DO_13 | DI_13 | 000013 | 13 | |
| | 14 | DO_14 | DI_14 | 000014 | 14 | |
| | 15 | DO_15 | DI_15 | 000015 | 15 | |
| | 16 | DO_16 | DI_16 | 000016 | 16 | |
| 2 | 17 | DO_17 | DI_17 | 000017 | 17 | 2 |
| | 18 | DO_18 | DI_18 | 000018 | 18 | |
| | 19 | DO_19 | DI_19 | 000019 | 19 | |
| | 20 | DO_20 | DI_20 | 000020 | 20 | |
| | 21 | DO_21 | DI_21 | 000021 | 21 | |
| | 22 | DO_22 | DI_22 | 000022 | 22 | |
| | 23 | DO_23 | DI_23 | 000023 | 23 | |
| | 24 | DO_24 | DI_24 | 000024 | 24 | |
| | 25 | DO_25 | DI_25 | 000025 | 25 | |
| | 26 | DO_26 | DI_26 | 000026 | 26 | |
| | 27 | DO_27 | DI_27 | 000027 | 27 | |
| | 28 | DO_28 | DI_28 | 000028 | 28 | |
| | 29 | DO_29 | DI_29 | 000029 | 29 | |
| | 30 | DO_30 | DI_30 | 000030 | 30 | |
| | 31 | DO_31 | DI_31 | 000031 | 31 | |
| | 32 | DO_32 | DI_32 | 000032 | 32 | |

| Analog input | | | | |
|-----------------|------------|----------------|---------|------|
| Client (master) | | Server (slave) | | |
| Word | Input name | Output name | Address | Word |
| 1 | AI_01 | AO_01 | 400001 | 1 |
| 2 | AI_02 | AO_02 | 400002 | 2 |
| 3 | AI_03 | AO_03 | 400003 | 3 |
| 4 | AI_04 | AO_04 | 400004 | 4 |

| Analog output | | | | |
|-----------------|-------------|----------------|---------|------|
| Client (master) | | Server (slave) | | |
| Word | Output name | Input name | Address | Word |
| 1 | AO_01 | AI_01 | 300001 | 1 |
| 2 | AO_02 | AI_02 | 300002 | 2 |
| 3 | AO_03 | AI_03 | 300003 | 3 |
| 4 | AO_04 | AI_04 | 300004 | 4 |

4 CS8C versus CS9 Modbus server

CS8C and CS9 Modbus server configuration are not compatible.

You will have to rebuild/adapt your configuration on both side (controller and equipment).

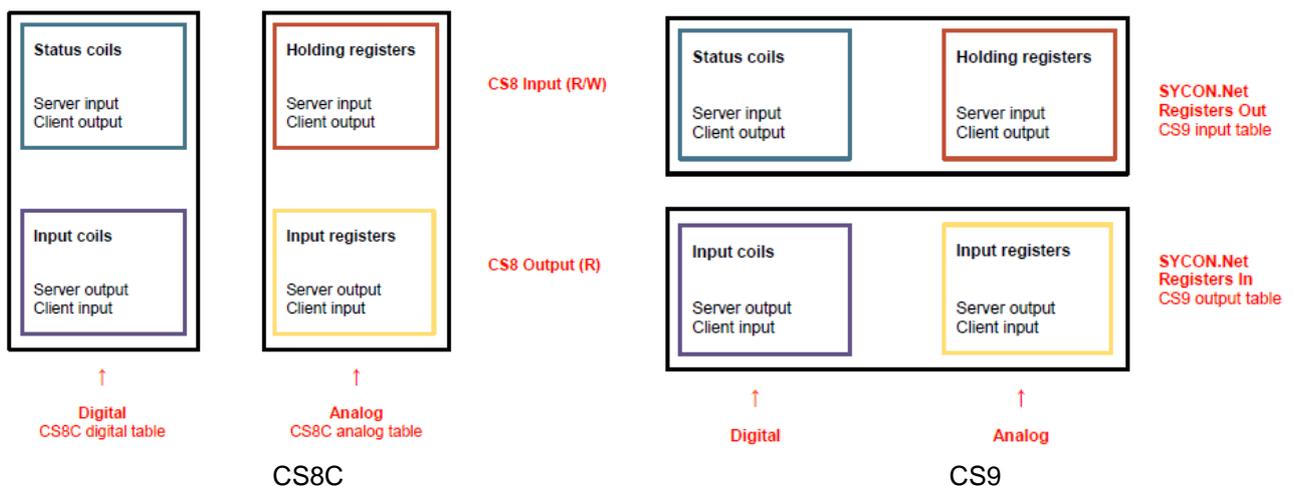
Modbus specification define only bit and word data types (coils/discrete input, holding register/input register). Other data types are manufacturer specific.

Modbus specification gives manufacturer a lot of leeway on how to manage/store data.

Some of CS8C and CS9 Modbus server configuration difference are:

- Different way of storing data:
 - CS8C use one table for bit and one for word
 - CS9 use one table for input and one table for output
 - CS9 use a different bit arrangement (8 to 15 and then 0 to 7)
- Different way of managing others data types: the two word used for float / real32 representation are reversed between CS8C and CS9.

4.1 Data storage illustration



4.2 Data types illustration

Here below a simple comparison done with Modbus doctor with the different data types. As you can see, to get the same value, Modbus doctor configuration need to be different between CS8C and CS9.

Modbus doctor (<https://www.kscada.com/modbusdoctor.html>) is a freeware, not supported by STÄUBLI, used only for easy illustration of the difference.

| CS8 | | | | | | | | | | | | | | |
|-------|----------|-------------|------------------------------------|----------------------|-------------------------|------------|------------|----------------|----------------|-----------------------------|--|---|-------------------------------|-----------------------|
| Type | Quantity | Nb register | Value | Byte 0 | Byte 1 | Byte 2 | Byte 3 | Register 0 | Register 1 | Modbus doctor configuration | | | | |
| bit | 16 | 1 | 15 0 10000000 00000010 32770 | 7 0 00000010 2 | 15 8 10000000 128 | | | 640 | | | | | | |
| word | 1 | 2 | 65534 65535 | 255 255 | 254 255 | | | 65534 65535 | | | | X | 16 bits word | 65534 65535 |
| dword | 1 | 2 | 4294967294 -3,1415 | 255 14 | 254 86 | 255 192 | 255 73 | 65534 3670 | 65535 16457 | | | X | 32 bits word 32 bits float | 4294967294 -3,1415 |
| float | 2 | 4 | 3,1415 | 14 86 | 86 64 | 192 73 | 73 3670 | 3670 16457 | | | | | 32 bits float | 3,1415 |

| CS9 | | | | | | | | | | | | | | |
|------------|----------|-------------|------------------------------------|----------------------|-------------------------|----------|----------|----------------|--------------|-----------------------------|--|---|--------------------------------|------------------------------|
| Type | Quantity | Nb register | Value | Byte 0 | Byte 1 | Byte 2 | Byte 3 | Register 0 | Register 1 | Modbus doctor configuration | | | | |
| bit | 16 | 1 | 15 0 10000000 00000010 32770 | 7 0 00000010 2 | 15 8 10000000 128 | | | 640 | | | | | | |
| byte | 2 | 1 | 1 255 | 1 255 | | | | 511 | | | | | | 8 bit byte 8 bit byte |
| signed8 | 2 | 1 | -128 127 | 128 127 | | | | 32895 | | | | | | 8 bit byte 8 bit byte |
| unsigned8 | 2 | 1 | 1 255 | 1 255 | | | | 511 | | | | | | 8 bit byte 8 bit byte |
| word | 1 | 1 | 65534 | 255 | 254 | | | 65534 | | | | X | 16 bits word | 65534 |
| signed16 | 2 | 2 | -32768 32767 | 128 127 | 0 255 | | | 32768 32767 | | | | | | 16 bits word 16 bits word |
| unsigned16 | 1 | 1 | 65534 | 255 | 254 | | | 65534 | | | | X | 16 bits word | 65534 |
| dword | 1 | 2 | 4294967294 | 255 | 255 | 255 | 254 | 65535 | 65534 | | | X | 32 bits word | 4294967294 |
| signed32 | 2 | 4 | -2147483648 2147483647 | 128 127 | 0 255 | 0 255 | 0 255 | 32768 32767 | 0 65535 | | | X | 32 bits word 32 bits word | -2147483648 2147483647 |
| unsigned32 | 1 | 2 | 4294967294 | 255 | 255 | 255 | 254 | 65535 | 65534 | | | X | 32 bits word | 4294967294 |
| real32 | 2 | 4 | -3,1415 3,1415 | 192 64 | 73 73 | 14 14 | 86 86 | 49225 16457 | 3670 3670 | | | X | 32 bits float 32 bits float | -3,1415 3,1415 |

Sign not taken into account by Modbus doctor on 8 bit byte

5 Modbus server on CS8C

Coils are merged internally in a single table with first the Status coils and then the Input coils.

From the CS8C point of view, first the digital input than the digital output.

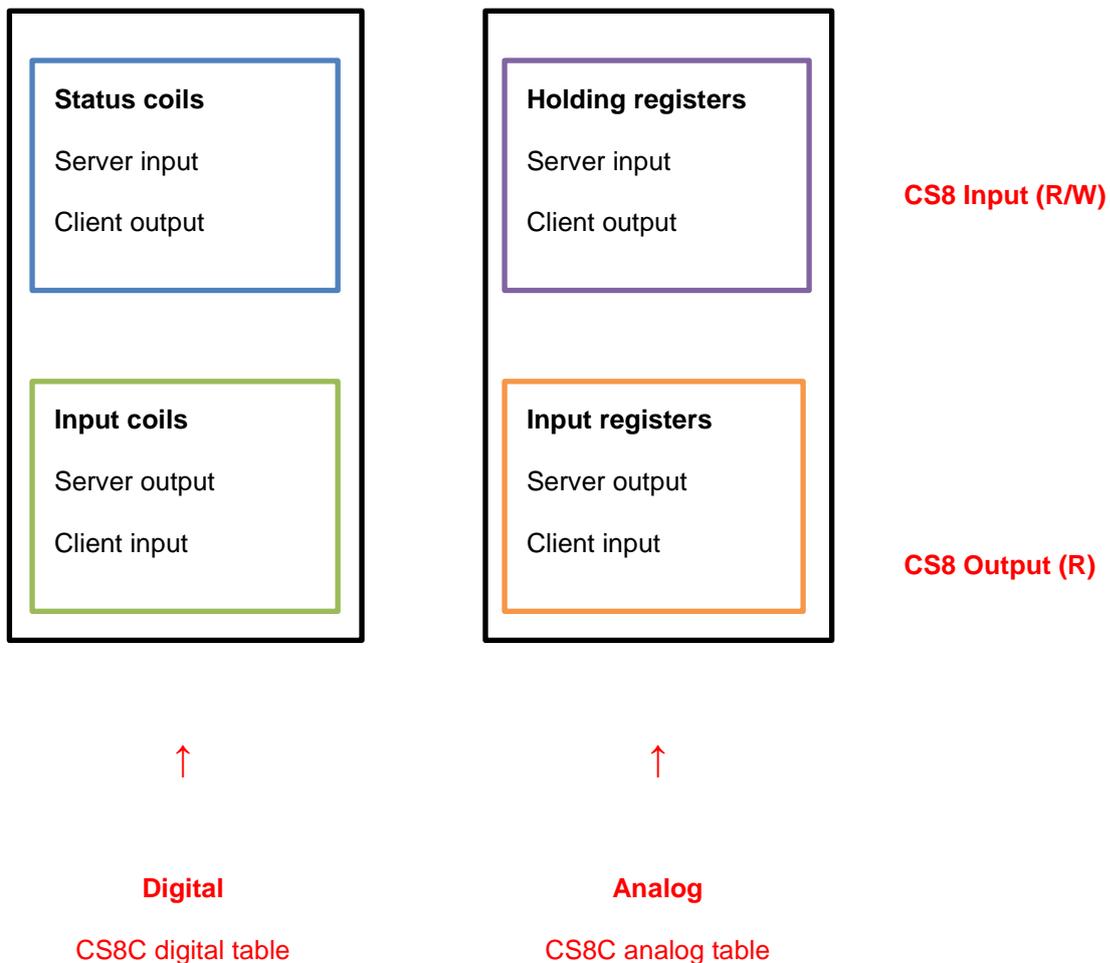
From the master point of view, first the digital output than the digital input.

Registers are merged internally in a single table with first the Holding registers and then the Input registers.

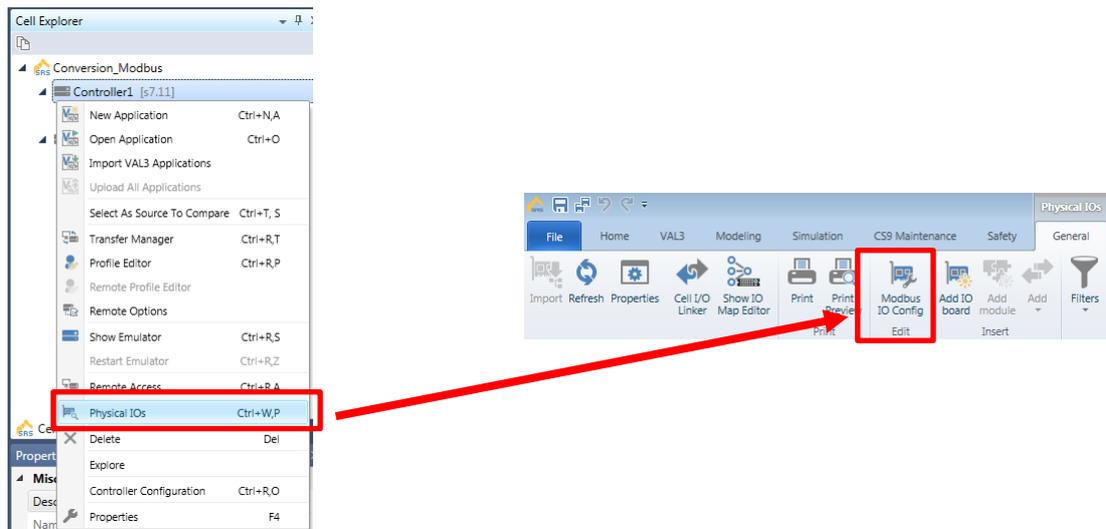
From the CS8C point of view, first the analog input than the analog output.

From the master point of view, first the analog output than the analog input.

Depending on what client equipment support, it could be interesting to have coils quantity as a multiple of 16 to prevent trouble with system managing only words.

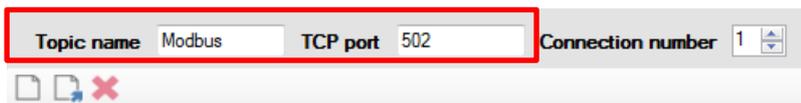


In SRS, select the controller in the cell explorer, make a right click on it and select “Physical IOs”, then “Modbus IO config”.



Do not change “Topic name” and “TCP port”.

Connection number can be adjust if needed (more than one client, client disconnections ...)



Add a new item at the bottom of the list

Add a new item above the selected item

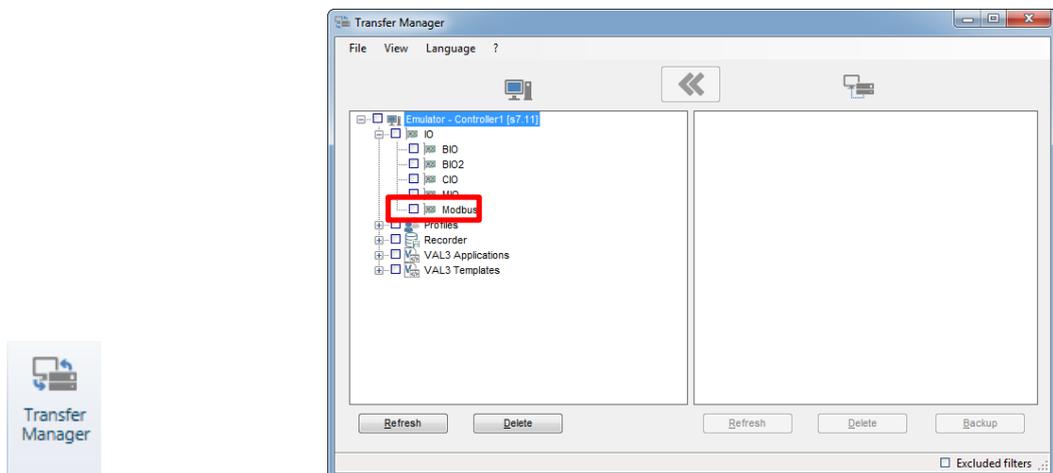
Delete the selected item

Do the proper configuration

Save it as “modbus.xml” (SRS place you in the right folder)

With “Transfer manager”, send the “Modbus” configuration to the controller.

Reboot the controller in order to take into account the new configuration.



5.1 Example with a PLC/screen configured as a client

In this example, the client has 12 digital outputs, 10 digital inputs, 2 analog outputs, 4 analog inputs.

In order to prevent issues we will round up digital outputs and inputs to the next 16 multiple.

| PLC / screen, client (master) | | | | CS8C, server (slave) | | | |
|-------------------------------|------|-----|-------------|----------------------|---------|-----|------|
| | Word | Bit | Output name | Input name | Address | Bit | Word |
| Digital output | 1 | 1 | DO_01 | DI_01 | 000001 | 1 | 1 |
| | | 2 | DO_02 | DI_02 | 000002 | 2 | |
| | | 3 | DO_03 | DI_03 | 000003 | 3 | |
| | | 4 | DO_04 | DI_04 | 000004 | 4 | |
| | | 5 | DO_05 | DI_05 | 000005 | 5 | |
| | | 6 | DO_06 | DI_06 | 000006 | 6 | |
| | | 7 | DO_07 | DI_07 | 000007 | 7 | |
| | | 8 | DO_08 | DI_08 | 000008 | 8 | |
| | | 9 | DO_09 | DI_09 | 000009 | 9 | |
| | | 10 | DO_10 | DI_10 | 000010 | 10 | |
| | | 11 | DO_11 | DI_11 | 000011 | 11 | |
| | | 12 | DO_12 | DI_12 | 000012 | 12 | |
| | | 13 | DO_free_01 | DI_free_01 | 000013 | 13 | |
| | | 14 | DO_free_02 | DI_free_02 | 000014 | 14 | |
| | | 15 | DO_free_03 | DI_free_03 | 000015 | 15 | |
| | | 16 | DO_free_03 | DI_free_04 | 000016 | 16 | |
| Digital input | 2 | 1 | DI_01 | DO_01 | 100017 | 17 | 2 |
| | | 2 | DI_02 | DO_02 | 100018 | 18 | |
| | | 3 | DI_03 | DO_03 | 100019 | 19 | |
| | | 4 | DI_04 | DO_04 | 100020 | 20 | |
| | | 5 | DI_05 | DO_05 | 100021 | 21 | |
| | | 6 | DI_06 | DO_06 | 100022 | 22 | |
| | | 7 | DI_07 | DO_07 | 100023 | 23 | |
| | | 8 | DI_08 | DO_08 | 100024 | 24 | |
| | | 9 | DI_09 | DO_09 | 100025 | 25 | |
| | | 10 | DI_10 | DO_10 | 100026 | 26 | |
| | | 11 | DI_free_01 | DO_free_01 | 100027 | 27 | |
| | | 12 | DI_free_02 | DO_free_02 | 100028 | 28 | |
| | | 13 | DI_free_03 | DO_free_03 | 100029 | 29 | |
| | | 14 | DI_free_04 | DO_free_04 | 100030 | 30 | |
| | | 15 | DI_free_05 | DO_free_05 | 100031 | 31 | |
| | | 16 | DI_free_06 | DO_free_06 | 100032 | 32 | |

| PLC / screen, client (master) | | | CS8C, server (slave) | | | |
|-------------------------------|------|------------|----------------------|---------|------|---------------|
| | Word | Input name | Output name | Address | Word | |
| Analog output | 1 | AO_01 | AI_01 | 300001 | 1 | Analog input |
| | 2 | AO_02 | AI_02 | 300002 | 2 | |
| Analog input | 1 | AI_01 | AO_01 | 400003 | 3 | Analog output |
| | 2 | AI_02 | AO_02 | 400004 | 4 | |
| | 3 | AI_03 | AO_03 | 400005 | 5 | |
| | 4 | AI_04 | AO_04 | 400006 | 6 | |

Start by adding 16 items that you configure as “bit” and “CS8 input (R/W)”. Name them properly; they will correspond to client digital outputs (12 digital outputs and 4 free to reach 16).

Add 16 items that you configure as “bit” and “CS8 output (R)”. Name them properly; they will correspond to client digital inputs (10 digital inputs and 6 free to reach 16).

Add 2 items that you configure as “word” and “CS8 input (R/W)”. Name them properly; they will correspond to client analog outputs (2 analog outputs).

Add 4 items that you configure as “word” and “CS8 output (R)”. Name them properly; they will correspond to client analog inputs (4 analog inputs).

You should get below result.

| Name | Type | Address | Size | Client Access |
|------------|------|---------|------|-----------------|
| DI_01 | BIT | 0 | 1 | CS8 Input (R/W) |
| DI_02 | BIT | 1 | 1 | CS8 Input (R/W) |
| DI_03 | BIT | 2 | 1 | CS8 Input (R/W) |
| DI_04 | BIT | 3 | 1 | CS8 Input (R/W) |
| DI_05 | BIT | 4 | 1 | CS8 Input (R/W) |
| DI_06 | BIT | 5 | 1 | CS8 Input (R/W) |
| DI_07 | BIT | 6 | 1 | CS8 Input (R/W) |
| DI_08 | BIT | 7 | 1 | CS8 Input (R/W) |
| DI_09 | BIT | 8 | 1 | CS8 Input (R/W) |
| DI_10 | BIT | 9 | 1 | CS8 Input (R/W) |
| DI_11 | BIT | 10 | 1 | CS8 Input (R/W) |
| DI_12 | BIT | 11 | 1 | CS8 Input (R/W) |
| DI_free_01 | BIT | 12 | 1 | CS8 Input (R/W) |
| DI_free_02 | BIT | 13 | 1 | CS8 Input (R/W) |
| DI_free_03 | BIT | 14 | 1 | CS8 Input (R/W) |
| DI_free_04 | BIT | 15 | 1 | CS8 Input (R/W) |
| DO_01 | BIT | 16 | 1 | CS8 Output (R) |
| DO_02 | BIT | 17 | 1 | CS8 Output (R) |
| DO_03 | BIT | 18 | 1 | CS8 Output (R) |
| DO_04 | BIT | 19 | 1 | CS8 Output (R) |
| DO_05 | BIT | 20 | 1 | CS8 Output (R) |
| DO_06 | BIT | 21 | 1 | CS8 Output (R) |
| DO_07 | BIT | 22 | 1 | CS8 Output (R) |
| DO_08 | BIT | 23 | 1 | CS8 Output (R) |
| DO_09 | BIT | 24 | 1 | CS8 Output (R) |
| DO_10 | BIT | 25 | 1 | CS8 Output (R) |
| DO_free_01 | BIT | 26 | 1 | CS8 Output (R) |
| DO_free_02 | BIT | 27 | 1 | CS8 Output (R) |
| DO_free_03 | BIT | 28 | 1 | CS8 Output (R) |
| DO_free_04 | BIT | 29 | 1 | CS8 Output (R) |
| DO_free_05 | BIT | 30 | 1 | CS8 Output (R) |
| DO_free_06 | BIT | 31 | 1 | CS8 Output (R) |
| AI_01 | WORD | 0 | 1 | CS8 Input (R/W) |
| AI_02 | WORD | 1 | 1 | CS8 Input (R/W) |
| AO_01 | WORD | 2 | 1 | CS8 Output (R) |
| AO_02 | WORD | 3 | 1 | CS8 Output (R) |
| AO_03 | WORD | 4 | 1 | CS8 Output (R) |
| AO_04 | WORD | 5 | 1 | CS8 Output (R) |

Save and close

You now have all your IOs available in SRS and you just have to link VAL3 variables with physical IOs.

| IO physiques | Description | Lien physique |
|----------------------------|-------------|-----------------------------------|
| ModbusSrv-0 | | |
| Modbus-Bit | | |
| Entrées digitales | | |
| DI_01 | %I10 | ModbusSrv-0\Modbus-Bit\DI_01 |
| DI_02 | %I11 | ModbusSrv-0\Modbus-Bit\DI_02 |
| DI_03 | %I12 | ModbusSrv-0\Modbus-Bit\DI_03 |
| DI_04 | %I13 | ModbusSrv-0\Modbus-Bit\DI_04 |
| DI_05 | %I14 | ModbusSrv-0\Modbus-Bit\DI_05 |
| DI_06 | %I15 | ModbusSrv-0\Modbus-Bit\DI_06 |
| DI_07 | %I16 | ModbusSrv-0\Modbus-Bit\DI_07 |
| DI_08 | %I17 | ModbusSrv-0\Modbus-Bit\DI_08 |
| DI_09 | %I18 | ModbusSrv-0\Modbus-Bit\DI_09 |
| DI_10 | %I19 | ModbusSrv-0\Modbus-Bit\DI_10 |
| DI_11 | %I10 | ModbusSrv-0\Modbus-Bit\DI_11 |
| DI_12 | %I11 | ModbusSrv-0\Modbus-Bit\DI_12 |
| DI_free_01 | %I12 | ModbusSrv-0\Modbus-Bit\DI_free_01 |
| DI_free_02 | %I13 | ModbusSrv-0\Modbus-Bit\DI_free_02 |
| DI_free_03 | %I14 | ModbusSrv-0\Modbus-Bit\DI_free_03 |
| DI_free_04 | %I15 | ModbusSrv-0\Modbus-Bit\DI_free_04 |
| Sorties digitales | | |
| DO_01 | %Q16 | ModbusSrv-0\Modbus-Bit\DO_01 |
| DO_02 | %Q17 | ModbusSrv-0\Modbus-Bit\DO_02 |
| DO_03 | %Q18 | ModbusSrv-0\Modbus-Bit\DO_03 |
| DO_04 | %Q19 | ModbusSrv-0\Modbus-Bit\DO_04 |
| DO_05 | %Q20 | ModbusSrv-0\Modbus-Bit\DO_05 |
| DO_06 | %Q21 | ModbusSrv-0\Modbus-Bit\DO_06 |
| DO_07 | %Q22 | ModbusSrv-0\Modbus-Bit\DO_07 |
| DO_08 | %Q23 | ModbusSrv-0\Modbus-Bit\DO_08 |
| DO_09 | %Q24 | ModbusSrv-0\Modbus-Bit\DO_09 |
| DO_10 | %Q25 | ModbusSrv-0\Modbus-Bit\DO_10 |
| DO_free_01 | %Q26 | ModbusSrv-0\Modbus-Bit\DO_free_01 |
| DO_free_02 | %Q27 | ModbusSrv-0\Modbus-Bit\DO_free_02 |
| DO_free_03 | %Q28 | ModbusSrv-0\Modbus-Bit\DO_free_03 |
| DO_free_04 | %Q29 | ModbusSrv-0\Modbus-Bit\DO_free_04 |
| DO_free_05 | %Q30 | ModbusSrv-0\Modbus-Bit\DO_free_05 |
| DO_free_06 | %Q31 | ModbusSrv-0\Modbus-Bit\DO_free_06 |
| Modbus-Word | | |
| Entrées analogiques | | |
| AI_01 | %IW0 | ModbusSrv-0\Modbus-Word\AI_01 |
| AI_02 | %IW1 | ModbusSrv-0\Modbus-Word\AI_02 |
| Sorties analogiques | | |
| AO_01 | %QW2 | ModbusSrv-0\Modbus-Word\AO_01 |
| AO_02 | %QW3 | ModbusSrv-0\Modbus-Word\AO_02 |
| AO_03 | %QW4 | ModbusSrv-0\Modbus-Word\AO_03 |
| AO_04 | %QW5 | ModbusSrv-0\Modbus-Word\AO_04 |

5.2 Example with a WAGO/STÄUBLI Modbus client (5109-8888)

That specific client has built-in:

- 2 bit output: a life bit and one unused
- 2 analog output: a version number and one unused

It is after those that, respectively, bit output then bit input and analog output then analog input appears.

We have 12 digital outputs, 10 digital inputs, 2 analog outputs, 4 analog inputs

| WAGO (5109-8888), client (master) | | | CS8C, server (slave) | | |
|-----------------------------------|-------|-------------|----------------------|-----|----------------|
| | Bit | Output name | Input name | Bit | |
| Digital output | 1 | LifeBit | LifeBit | 1 | Digital input |
| | 2 | NullBit | NullBit | 2 | |
| | 3 | DO_01 | DI_01 | 3 | |
| | 4 | DO_02 | DI_02 | 4 | |
| | 5 | DO_03 | DI_03 | 5 | |
| | 6 | DO_04 | DI_04 | 6 | |
| | 7 | DO_05 | DI_05 | 7 | |
| | 8 | DO_06 | DI_06 | 8 | |
| | 9 | DO_07 | DI_07 | 9 | |
| | 10 | DO_08 | DI_08 | 10 | |
| | 11 | DO_09 | DI_09 | 11 | |
| | 12 | DO_10 | DI_10 | 12 | |
| Digital input | 13 | DO_11 | DI_11 | 13 | Digital output |
| | 14 | DO_12 | DI_12 | 14 | |
| | 1 | DI_01 | DO_01 | 15 | |
| | 2 | DI_02 | DO_02 | 16 | |
| | 3 | DI_03 | DO_03 | 17 | |
| | 4 | DI_04 | DO_04 | 18 | |
| | 5 | DI_05 | DO_05 | 19 | |
| | 6 | DI_06 | DO_06 | 20 | |
| | 7 | DI_07 | DO_07 | 21 | |
| | 8 | DI_08 | DO_08 | 22 | |
| 9 | DI_09 | DO_09 | 23 | | |
| 10 | DI_10 | DO_10 | 24 | | |

| WAGO (5109-8888), client (master) | | | CS8C, server (slave) | | |
|-----------------------------------|------|------------|----------------------|------|---------------|
| | Word | Input name | Output name | Word | |
| Analog output | 1 | mbVersion | mbVersion | 1 | Analog input |
| | 2 | mbUnused | mbUnused | 2 | |
| | 3 | AO_01 | AI_01 | 3 | |
| | 4 | AO_02 | AI_02 | 4 | |
| Analog input | 1 | AI_01 | AO_01 | 5 | Analog output |
| | 2 | AI_02 | AO_02 | 6 | |
| | 3 | AI_03 | AO_03 | 7 | |
| | 4 | AI_04 | AO_04 | 8 | |

Start by adding 2 items that you configure as “bit” and “CS8 input (R/W)”. Name them respectively LifeBit and NullBit, they correspond to 2 internal bit of WAGO 5109-8888.

Add 12 items that you configure as “bit” and “CS8 input (R/W)”. Name them properly; they will correspond to WAGO 5109-8888 digital outputs.

Add 10 items that you configure as “bit” and “CS8 output (R)”. Name them properly; they will correspond to WAGO 5109-8888 digital inputs.

Add 2 items that you configure as “word” and “CS8 input (R/W)”. Name them respectively mbVersion and mbUnused.

Add 2 items that you configure as “word” and “CS8 input (R/W)”. Name them properly; they will correspond to WAGO 5109-8888 analog outputs (2 analog outputs).

Add 4 items that you configure as “word” and “CS8 output (R)”. Name them properly; they will correspond to WAGO 5109-8888 analog inputs (4 analog inputs).

You should get below result.

The screenshot shows the 'Stäubli Modbus IO Config' window. At the top, the 'Topic name' is 'Modbus', 'TCP port' is '502', and 'Connection number' is '1'. Below this is a table with the following columns: Name, Type, Address, Size, and Client Access. The table contains 30 rows of configurations:

| Name | Type | Address | Size | Client Access |
|-----------|------|---------|------|-----------------|
| LifeBit | BIT | 0 | 1 | CS8 Input (R/W) |
| NullBit | BIT | 1 | 1 | CS8 Input (R/W) |
| DI_01 | BIT | 2 | 1 | CS8 Input (R/W) |
| DI_02 | BIT | 3 | 1 | CS8 Input (R/W) |
| DI_03 | BIT | 4 | 1 | CS8 Input (R/W) |
| DI_04 | BIT | 5 | 1 | CS8 Input (R/W) |
| DI_05 | BIT | 6 | 1 | CS8 Input (R/W) |
| DI_06 | BIT | 7 | 1 | CS8 Input (R/W) |
| DI_07 | BIT | 8 | 1 | CS8 Input (R/W) |
| DI_08 | BIT | 9 | 1 | CS8 Input (R/W) |
| DI_09 | BIT | 10 | 1 | CS8 Input (R/W) |
| DI_10 | BIT | 11 | 1 | CS8 Input (R/W) |
| DI_11 | BIT | 12 | 1 | CS8 Input (R/W) |
| DI_12 | BIT | 13 | 1 | CS8 Input (R/W) |
| DO_01 | BIT | 14 | 1 | CS8 Output (R) |
| DO_02 | BIT | 15 | 1 | CS8 Output (R) |
| DO_03 | BIT | 16 | 1 | CS8 Output (R) |
| DO_04 | BIT | 17 | 1 | CS8 Output (R) |
| DO_05 | BIT | 18 | 1 | CS8 Output (R) |
| DO_06 | BIT | 19 | 1 | CS8 Output (R) |
| DO_07 | BIT | 20 | 1 | CS8 Output (R) |
| DO_08 | BIT | 21 | 1 | CS8 Output (R) |
| DO_09 | BIT | 22 | 1 | CS8 Output (R) |
| DO_10 | BIT | 23 | 1 | CS8 Output (R) |
| mbVersion | WORD | 0 | 1 | CS8 Input (R/W) |
| mbUnused | WORD | 1 | 1 | CS8 Input (R/W) |
| AI_01 | WORD | 2 | 1 | CS8 Input (R/W) |
| AI_02 | WORD | 3 | 1 | CS8 Input (R/W) |
| AO_01 | WORD | 4 | 1 | CS8 Output (R) |
| AO_02 | WORD | 5 | 1 | CS8 Output (R) |
| AO_03 | WORD | 6 | 1 | CS8 Output (R) |
| AO_04 | WORD | 7 | 1 | CS8 Output (R) |

The status bar at the bottom shows the file path: C:\Users\ajaf\Documents\Stäubli\SRS\Test\Conversion_Modbus\Controlle1\usr\applicom\modbus\modbus.xml

You now have all your IOs available in SRS and you just have to link VAL3 variables with physical IOs.

| IO physiques | Description | Lien physique |
|---------------------|-------------|-----------------------------------|
| ModbusSrv-0 | | |
| Modbus-Bit | | |
| Entrées digitales | | |
| LifeBit | %I0 | ModbusSrv-0\Modbus-Bit\LifeBit |
| NullBit | %I1 | ModbusSrv-0\Modbus-Bit\NullBit |
| DI_01 | %I2 | ModbusSrv-0\Modbus-Bit\DI_01 |
| DI_02 | %I3 | ModbusSrv-0\Modbus-Bit\DI_02 |
| DI_03 | %I4 | ModbusSrv-0\Modbus-Bit\DI_03 |
| DI_04 | %I5 | ModbusSrv-0\Modbus-Bit\DI_04 |
| DI_05 | %I6 | ModbusSrv-0\Modbus-Bit\DI_05 |
| DI_06 | %I7 | ModbusSrv-0\Modbus-Bit\DI_06 |
| DI_07 | %I8 | ModbusSrv-0\Modbus-Bit\DI_07 |
| DI_08 | %I9 | ModbusSrv-0\Modbus-Bit\DI_08 |
| DI_09 | %I10 | ModbusSrv-0\Modbus-Bit\DI_09 |
| DI_10 | %I11 | ModbusSrv-0\Modbus-Bit\DI_10 |
| DI_11 | %I12 | ModbusSrv-0\Modbus-Bit\DI_11 |
| DI_12 | %I13 | ModbusSrv-0\Modbus-Bit\DI_12 |
| Sorties digitales | | |
| DO_01 | %Q14 | ModbusSrv-0\Modbus-Bit\DO_01 |
| DO_02 | %Q15 | ModbusSrv-0\Modbus-Bit\DO_02 |
| DO_03 | %Q16 | ModbusSrv-0\Modbus-Bit\DO_03 |
| DO_04 | %Q17 | ModbusSrv-0\Modbus-Bit\DO_04 |
| DO_05 | %Q18 | ModbusSrv-0\Modbus-Bit\DO_05 |
| DO_06 | %Q19 | ModbusSrv-0\Modbus-Bit\DO_06 |
| DO_07 | %Q20 | ModbusSrv-0\Modbus-Bit\DO_07 |
| DO_08 | %Q21 | ModbusSrv-0\Modbus-Bit\DO_08 |
| DO_09 | %Q22 | ModbusSrv-0\Modbus-Bit\DO_09 |
| DO_10 | %Q23 | ModbusSrv-0\Modbus-Bit\DO_10 |
| Modbus-Word | | |
| Entrées analogiques | | |
| mbVersion | %IW0 | ModbusSrv-0\Modbus-Word\mbVersion |
| mbUnused | %IW1 | ModbusSrv-0\Modbus-Word\mbUnused |
| AI_01 | %IW2 | ModbusSrv-0\Modbus-Word\AI_01 |
| AI_02 | %IW3 | ModbusSrv-0\Modbus-Word\AI_02 |
| Sorties analogiques | | |
| AO_01 | %QW4 | ModbusSrv-0\Modbus-Word\AO_01 |
| AO_02 | %QW5 | ModbusSrv-0\Modbus-Word\AO_02 |
| AO_03 | %QW6 | ModbusSrv-0\Modbus-Word\AO_03 |
| AO_04 | %QW7 | ModbusSrv-0\Modbus-Word\AO_04 |

Below, corresponding WAGO coupler configuration set to use automatic configuration.

Login: admin

Password: wago

WAGO
INNOVATIVE CONNECTIONS

Web-based Management

WAGO Kontakttechnik GmbH & Co. KG
Hansstr. 27
D-32423 Minden
www.wago.com

Navigation

- Information
- TCP/IP
- IO config
- Stäubli

Stäubli configuration

This page is for the configuration of the communication settings. Changes will take effect immediately.

Settings

| | | | | |
|---|------|-----|--------|-----|
| Stäubli controller IP address | 192 | 168 | 0 | 254 |
| Configuration byte | 67 | | | |
| Modbus/TCP timeout [ms] | 50 | | | |
| | AUTO | | CUSTOM | |
| Analog input address (WORD - R/W) | 0 | | 1 | |
| Analog output address (WORD - R) | 4 | | 1 | |
| Digital input address (BIT - R/W) | 0 | | 0 | |
| Digital output address (BIT - R) | 14 | | 0 | |
| Use custom configuration (0 = AUTO, 1 = CUSTOM) | | | 0 | |

UNDO SUBMIT

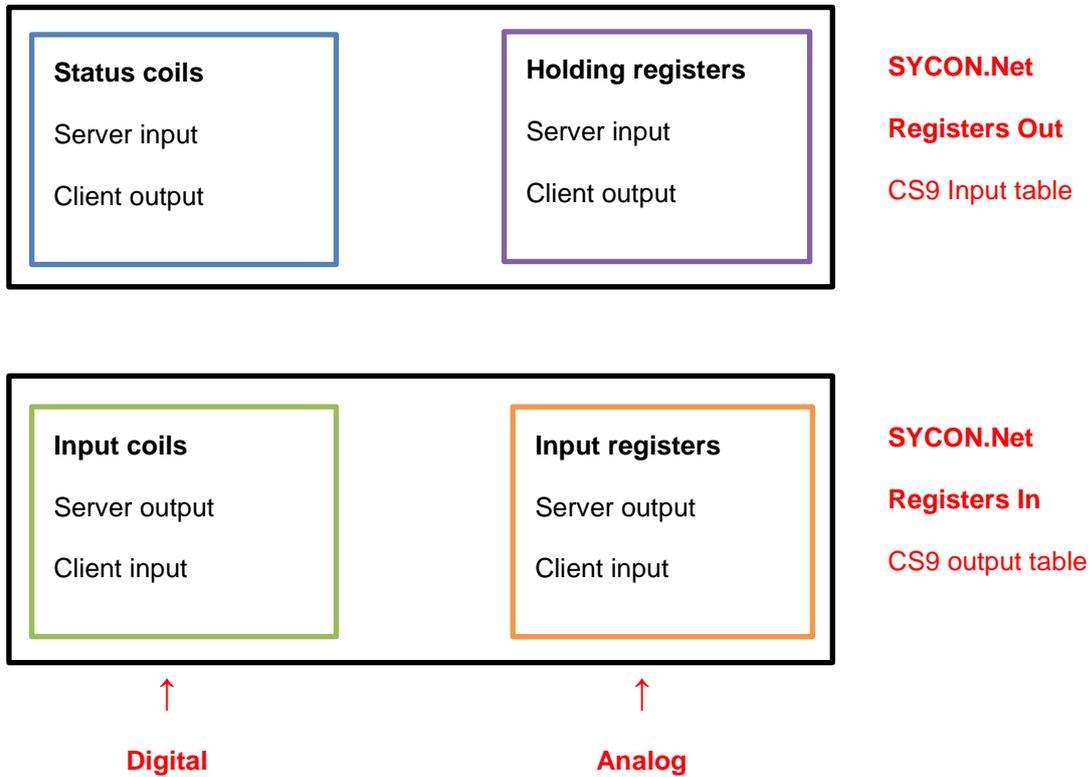
6 Modbus server on CS9

All is managed internally as word but stored as 2 bytes.

Holding registers follow status coils in a single table.

Input registers follow input coils in a single table.

That is why you must always have a multiple of 16 for coils to fill a word multiple.

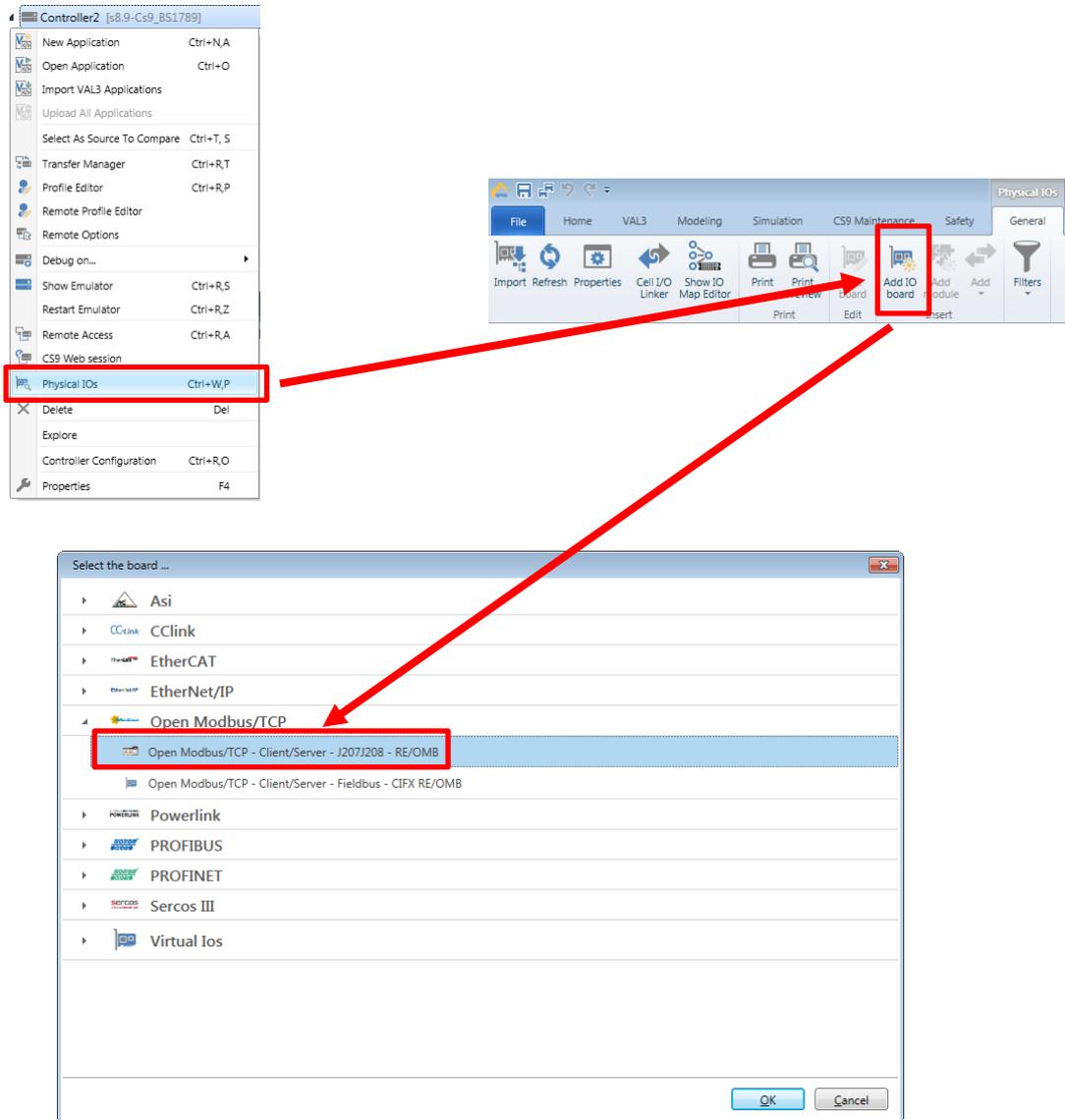


For data transmission, Modbus protocol specify that values must be encoded as big endian (Most Significant Byte first then Last Significant Byte).

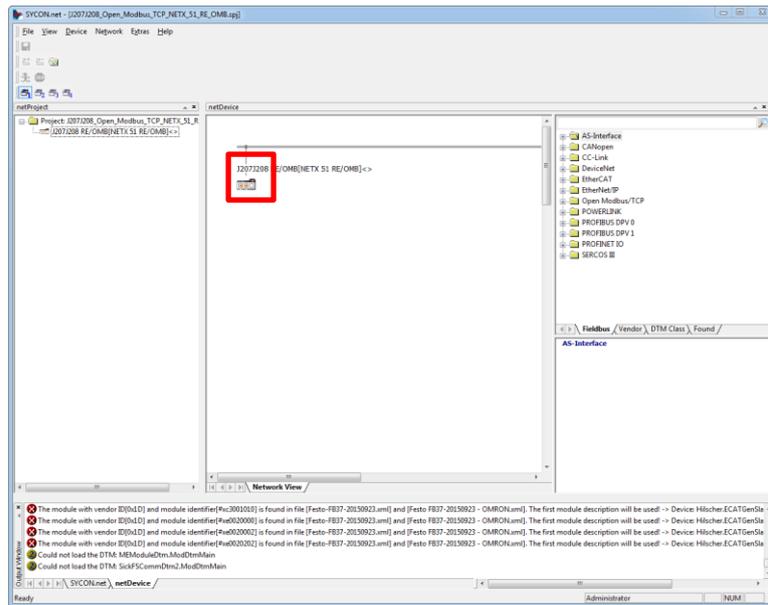
On CS9 this also apply on coils for their internal storage, thus you will have a swap between first 8 coils and last 8 coils:

| | | | | | | | | | | | | | | | | |
|------|---|----|----|----|----|----|----|----|---|---|----|----|----|----|----|----|
| Bit | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
| Coil | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |

In SRS, select the controller in the cell explorer, make a right click on it and select “Physical IOs”, “Add IO board”, “Open Modbus/TCP – Client/Server – J207/J208 – RE/OMB”



This open SYCON.net. Double click on J207/J208

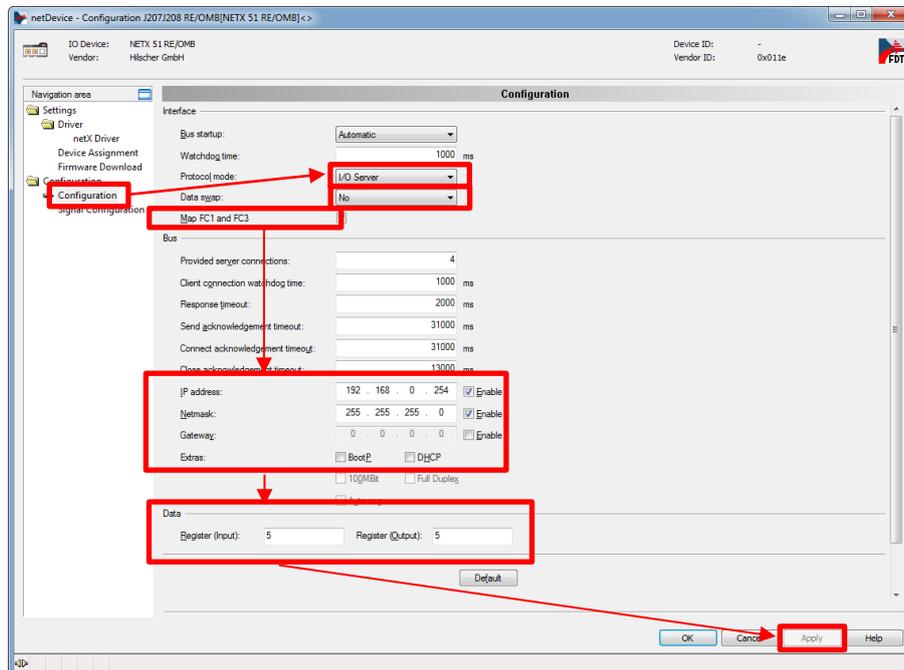


Select “Configuration” branch, select “I/O Server”. Check “Map FC1 and FC3” if input and output are merged in a single table (one for digital IO, one for analog IO).

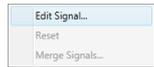
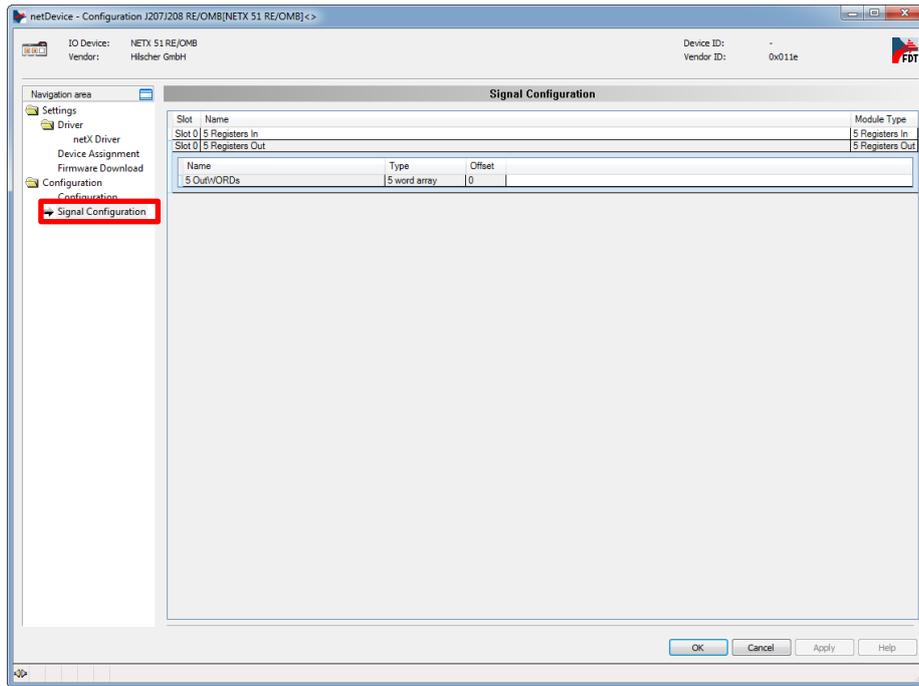
Uncheck “DHCP”, enable and set “IP address” and “Netmask”. Here, you specify the server IP address.

Fill “Register Input” and “Register Output” size. Be careful as all detailed configuration you will do on next step will be lost if you change those values.

“Apply”.



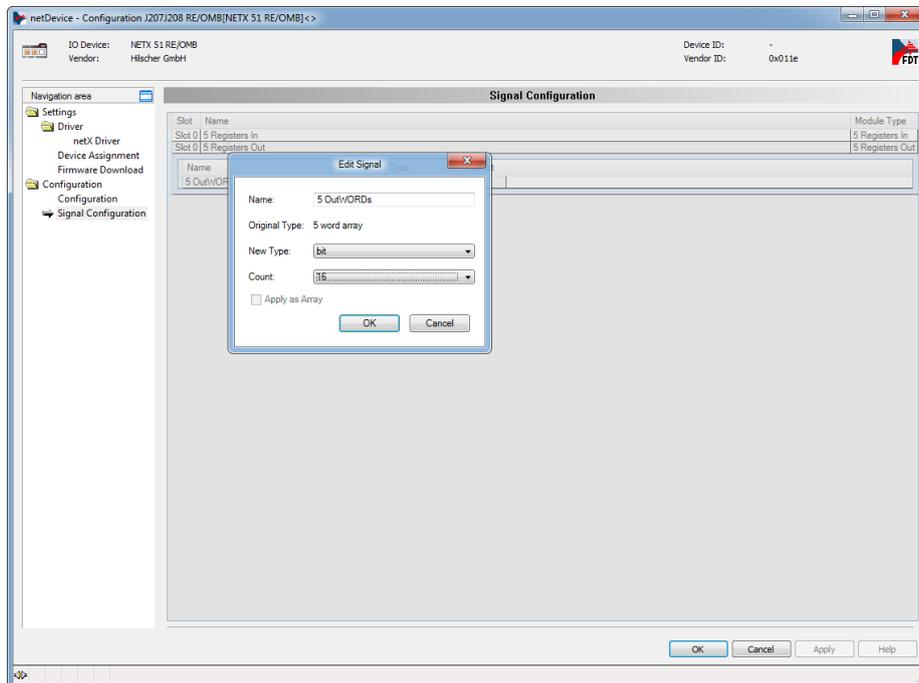
Select “Signal Configuration” branch to access word arrays, which has been built.



Right click on the array and select “Edit Signal”

You can now split / merge / rename items.

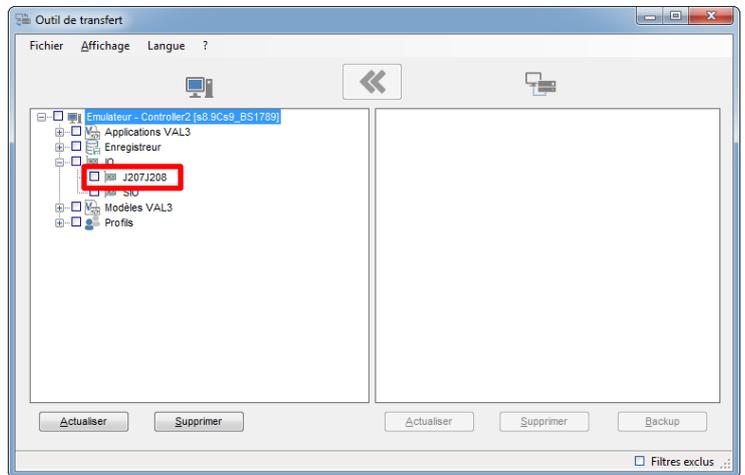
Press “Apply” after each change to do it.



When finished, press “Ok” then “File”, “Save” and close SYCON.

With “Transfer manager”, send the “J207/J208” configuration to the controller.

Reboot the controller in order to take into account the new configuration.



6.1 Example with a PLC/screen configured as a client

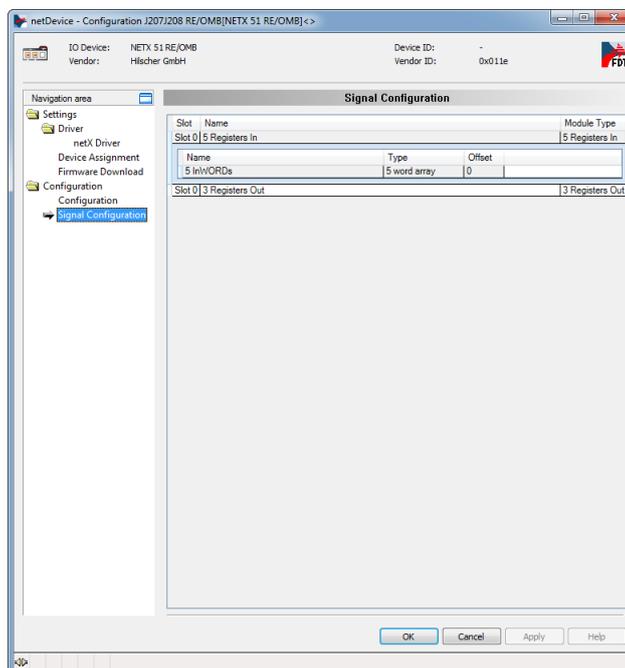
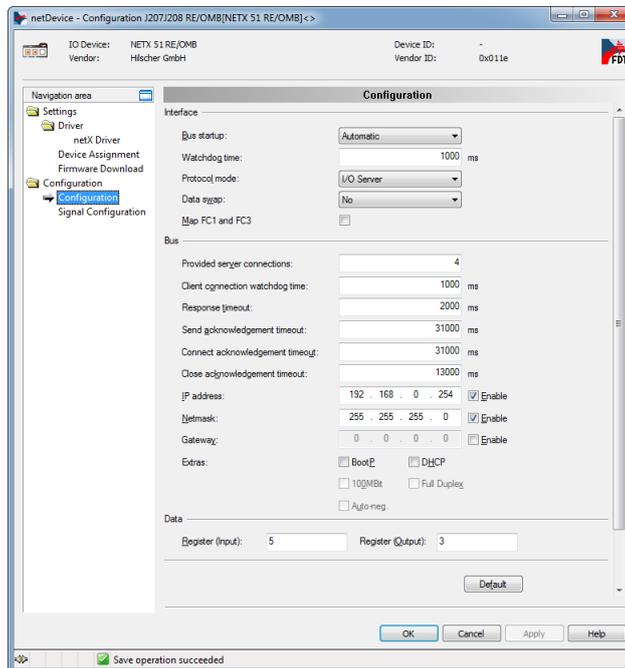
In this example, the client has 12 digital outputs, 10 digital inputs, 2 analog outputs, 4 analog inputs.

In order to prevent issues we will round up digital outputs and inputs to the next 16 multiple.

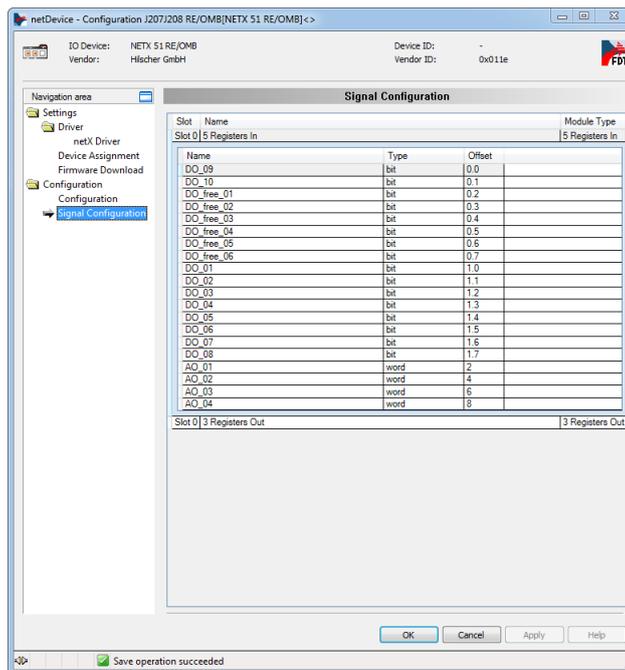
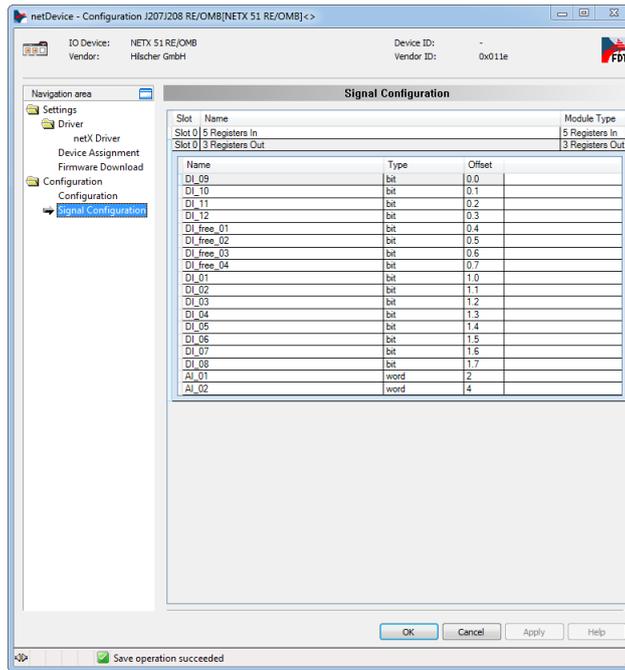
| PLC / screen, client (master) | | | | CS9, server (slave) | | | |
|-------------------------------|-----|-------------|------------|---------------------|--------|------|---------------|
| Word | Bit | Output name | Input name | Address | Bit | Word | |
| Digital output | 1 | 1 | DO_01 | DI_01 | 000009 | 9 | Digital input |
| | | 2 | DO_02 | DI_02 | 000010 | 10 | |
| | | 3 | DO_03 | DI_03 | 000011 | 11 | |
| | | 4 | DO_04 | DI_04 | 000012 | 12 | |
| | | 5 | DO_05 | DI_05 | 000013 | 13 | |
| | | 6 | DO_06 | DI_06 | 000014 | 14 | |
| | | 7 | DO_07 | DI_07 | 000015 | 15 | |
| | | 8 | DO_08 | DI_08 | 000016 | 16 | |
| | | 9 | DO_09 | DI_09 | 000001 | 1 | |
| | | 10 | DO_10 | DI_10 | 000002 | 2 | |
| | | 11 | DO_11 | DI_11 | 000003 | 3 | |
| | | 12 | DO_12 | DI_12 | 000004 | 4 | |
| | | 13 | DO_free_01 | DI_free_01 | 000005 | 5 | |
| | | 14 | DO_free_02 | DI_free_02 | 000006 | 6 | |
| | | 15 | DO_free_03 | DI_free_03 | 000007 | 7 | |
| | | 16 | DO_free_04 | DI_free_04 | 000008 | 8 | |
| Analog output | 2 | AO_01 | AI_01 | 300002 | | 2 | Analog input |
| | 3 | AO_02 | AI_02 | 300003 | | 3 | |

| PLC / screen, client (master) | | | | CS9, server (slave) | | | |
|-------------------------------|-----|-------------|------------|---------------------|--------|------|----------------|
| Word | Bit | Output name | Input name | Address | Bit | Word | |
| Digital input | 1 | 1 | DI_01 | DO_01 | 100009 | 9 | Digital output |
| | | 2 | DI_02 | DO_02 | 100010 | 10 | |
| | | 3 | DI_03 | DO_03 | 100011 | 11 | |
| | | 4 | DI_04 | DO_04 | 100012 | 12 | |
| | | 5 | DI_05 | DO_05 | 100013 | 13 | |
| | | 6 | DI_06 | DO_06 | 100014 | 14 | |
| | | 7 | DI_07 | DO_07 | 100015 | 15 | |
| | | 8 | DI_08 | DO_08 | 100016 | 16 | |
| | | 9 | DI_09 | DO_09 | 100001 | 1 | |
| | | 10 | DI_10 | DO_10 | 100002 | 2 | |
| | | 11 | DI_free_01 | DO_free_01 | 100003 | 3 | |
| | | 12 | DI_free_02 | DO_free_02 | 100004 | 4 | |
| | | 13 | DI_free_03 | DO_free_03 | 100005 | 5 | |
| | | 14 | DI_free_04 | DO_free_04 | 100006 | 6 | |
| | | 15 | DI_free_05 | DO_free_05 | 100007 | 7 | |
| | | 16 | DI_free_06 | DO_free_06 | 100008 | 8 | |
| Analog input | 2 | AI_01 | AO_01 | 400002 | | 2 | Analog output |
| | 3 | AI_02 | AO_02 | 400003 | | 3 | |
| | 4 | AI_03 | AO_03 | 400004 | | 4 | |
| | 5 | AI_04 | AO_04 | 400005 | | 5 | |

Above exchange table shows that we need 5 register (input) and 3 register (output).



In "Signal Configuration", split "Registers In" and "Registers Out" as defined in the exchange table.



You now have all your IOs available in SRS and you just have to link VAL3 variables with physical IOs.

| IO physiques | Description | Lien physique |
|---------------------|-------------|--------------------------------------|
| J207J208 RE/OMB | J207/J208 | |
| Entrées digitales | | |
| %I0 | DI_09 | CCCE5CD8-ABC1-48DF-9290-64D69510C130 |
| %I1 | DI_10 | 0EF46B70-1E45-4291-9BE1-16DFB9F48BD1 |
| %I2 | DI_11 | 493D689D-3018-47EC-900D-052832CB05B2 |
| %I3 | DI_12 | 8C5B3FC8-4BF7-4B00-8B4D-CF270FE480B8 |
| %I4 | DI_free_01 | DCF15D7A-3752-4B3B-BC29-E1C752ADF7CA |
| %I5 | DI_free_02 | CF2A08EF-7A04-4E9E-84D1-22BA9DD4D7BE |
| %I6 | DI_free_03 | 91EF4FFF-10E2-4832-A8F1-76BD5B50F474 |
| %I7 | DI_free_04 | 3A5E439B-3F2A-45AF-839C-D6F619C87422 |
| %I8 | DI_01 | 0654104C-2915-4E11-84E7-35B8D2EEC696 |
| %I9 | DI_02 | F212DD5F-794B-474E-A2C9-3F70A60812D1 |
| %I10 | DI_03 | 1361AB3C-AD62-40B6-940F-7E4A4201646D |
| %I11 | DI_04 | 9C0706DA-B257-4A9C-AED4-D12BF718338D |
| %I12 | DI_05 | 68E8231A-A2CF-4436-9D9B-8CC3674D4E3D |
| %I13 | DI_06 | 56B4859D-A3A9-4484-BAE3-72A6A7812EB1 |
| %I14 | DI_07 | 227FC60D-86DD-4076-B496-6A5F3E95BD32 |
| %I15 | DI_08 | 846C64EE-5847-4E16-881C-4B88A9B53539 |
| Sorties digitales | | |
| %Q0 | DO_09 | 4A310D3A-62C0-4AB8-9B8D-894E881D2B7A |
| %Q1 | DO_10 | 62ABB1F4-FD17-4354-A645-C262A5CE6C54 |
| %Q2 | DO_free_01 | F27CC68B-6285-4678-BF73-5DD128FF904E |
| %Q3 | DO_free_02 | 7E10C8E4-1E7D-4660-A071-9378E34BE1CB |
| %Q4 | DO_free_03 | BA9F2C72-ED1B-4EE7-B964-481598AF3877 |
| %Q5 | DO_free_04 | BC444DC7-0C5F-41FD-B856-991CDD9C7F9F |
| %Q6 | DO_free_05 | A9B7B449-EAFA-4CCF-AF8E-BB7B53FE9DCC |
| %Q7 | DO_free_06 | AAD94247-863B-4F1F-B6F7-D4E53AF3F8AE |
| %Q8 | DO_01 | 11DD89FD-1401-460A-8FA4-29040348CC30 |
| %Q9 | DO_02 | 1C1238E2-D266-47A1-9978-2B954FE36B28 |
| %Q10 | DO_03 | DA10CD9F-D857-4A61-AB9F-4C98CC142F7D |
| %Q11 | DO_04 | 2AD7B019-8E61-4FE1-B2A2-C41553A41098 |
| %Q12 | DO_05 | 890449F7-72BE-4A3B-A13A-20D67AA8B3B2 |
| %Q13 | DO_06 | 0E061E2F-A5A1-4C6F-9436-36B3FE1F6326 |
| %Q14 | DO_07 | E0F8ACF3-B3F3-4FFB-A35D-87FAC8FE0809 |
| %Q15 | DO_08 | 8F025D8B-EEBE-4379-B7F2-D6FE45563786 |
| Entrées analogiques | | |
| %IW16 | AI_01 | 4A8176D9-F8C6-43AF-A230-4632D083538E |
| %IW32 | AI_02 | 2E1EF23A-9839-491F-888D-DAB21406D6C0 |
| Sorties analogiques | | |
| %QW16 | AO_01 | A7E4A964-84F4-4672-9298-346A1315AC49 |
| %QW32 | AO_02 | FD67CCA8-33D5-458A-88DC-28C2DC686DE |
| %QW48 | AO_03 | 25EB93A3-28D0-4B7B-990A-123E3F9E64F9 |
| %QW64 | AO_04 | AED68889-25DE-4AD8-B211-896561619DF9 |

6.2 Example with a WAGO/STÄUBLI Modbus client (5109-8888)

That specific client has built-in:

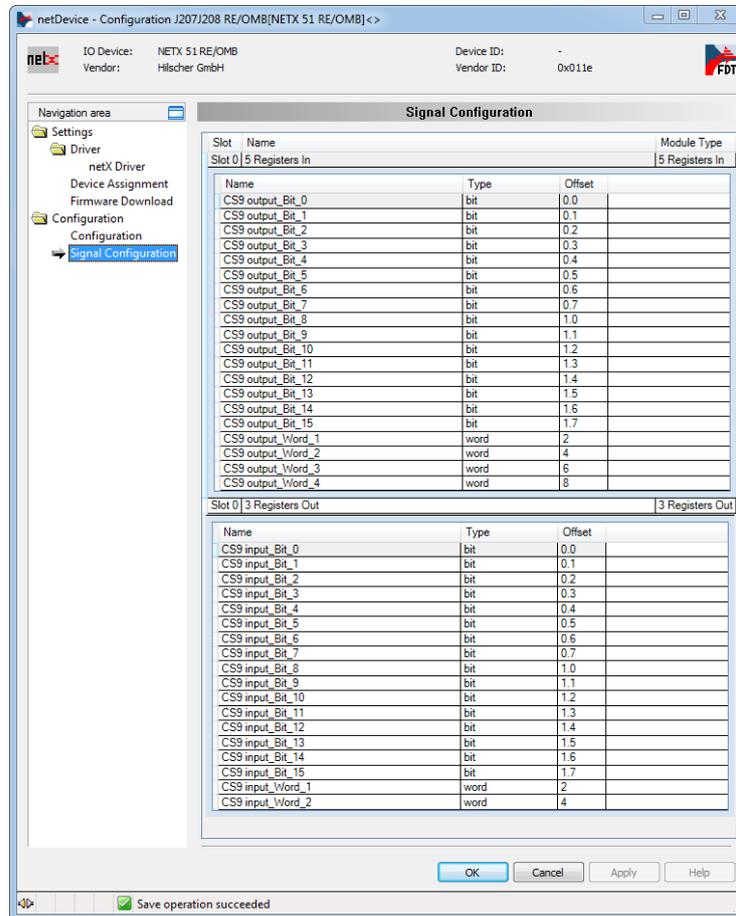
- 2 bit output: a life bit and one unused
- 2 analog output: a version number and one unused

We have 12 digital outputs, 10 digital inputs, 2 analog outputs, 4 analog inputs

| WAGO (5109-8888), client (master) | | | | CS9, server (slave) | | | |
|-----------------------------------|------|-----|-------------|---------------------|-----|------|---------------|
| | Word | Bit | Output name | Input name | Bit | Word | |
| Digital output | 1 | 1 | LifeBit | LifeBit | 9 | 1 | Digital input |
| | | 2 | NullBit | NullBit | 10 | | |
| | | 3 | DO_01 | DI_01 | 11 | | |
| | | 4 | DO_02 | DI_02 | 12 | | |
| | | 5 | DO_03 | DI_03 | 13 | | |
| | | 6 | DO_04 | DI_04 | 14 | | |
| | | 7 | DO_05 | DI_05 | 15 | | |
| | | 8 | DO_06 | DI_06 | 16 | | |
| | | 9 | DO_07 | DI_07 | 1 | | |
| | | 10 | DO_08 | DI_08 | 2 | | |
| | | 11 | DO_09 | DI_09 | 3 | | |
| | | 12 | DO_10 | DI_10 | 4 | | |
| | | 13 | DO_11 | DI_11 | 5 | | |
| | | 14 | DO_12 | DI_12 | 6 | | |
| | | 15 | DO_free_01 | DI_free_01 | 7 | | |
| | | 16 | DO_free_02 | DI_free_02 | 8 | | |
| Analog output | 2 | | mbVersion | mbVersion | | 2 | Analog input |
| | 3 | | mbUnused | mbUnused | | 3 | |
| | 4 | | AO_01 | AI_01 | | 4 | |
| | 5 | | AO_02 | AI_02 | | 5 | |

| WAGO (5109-8888), client (master) | | | | CS9, server (slave) | | | |
|-----------------------------------|------|-----|-------------|---------------------|-----|------|----------------|
| | Word | Bit | Output name | Input name | Bit | Word | |
| Digital input | 1 | 1 | DI_01 | DO_01 | 9 | 1 | Digital output |
| | | 2 | DI_02 | DO_02 | 10 | | |
| | | 3 | DI_03 | DO_03 | 11 | | |
| | | 4 | DI_04 | DO_04 | 12 | | |
| | | 5 | DI_05 | DO_05 | 13 | | |
| | | 6 | DI_06 | DO_06 | 14 | | |
| | | 7 | DI_07 | DO_07 | 15 | | |
| | | 8 | DI_08 | DO_08 | 16 | | |
| | | 9 | DI_09 | DO_09 | 1 | | |
| | | 10 | DI_10 | DO_10 | 2 | | |
| | | 11 | DI_free_01 | DO_free_01 | 3 | | |
| | | 12 | DI_free_02 | DO_free_02 | 4 | | |
| | | 13 | DI_free_03 | DO_free_03 | 5 | | |
| | | 14 | DI_free_04 | DO_free_04 | 6 | | |
| | | 15 | DI_free_05 | DO_free_05 | 7 | | |
| | | 16 | DI_free_06 | DO_free_06 | 8 | | |
| Analog input | 2 | | AI_01 | AO_01 | | 2 | Analog output |
| | 3 | | AI_02 | AO_02 | | 3 | |
| | 4 | | AI_03 | AO_03 | | 4 | |
| | 5 | | AI_04 | AO_04 | | 5 | |

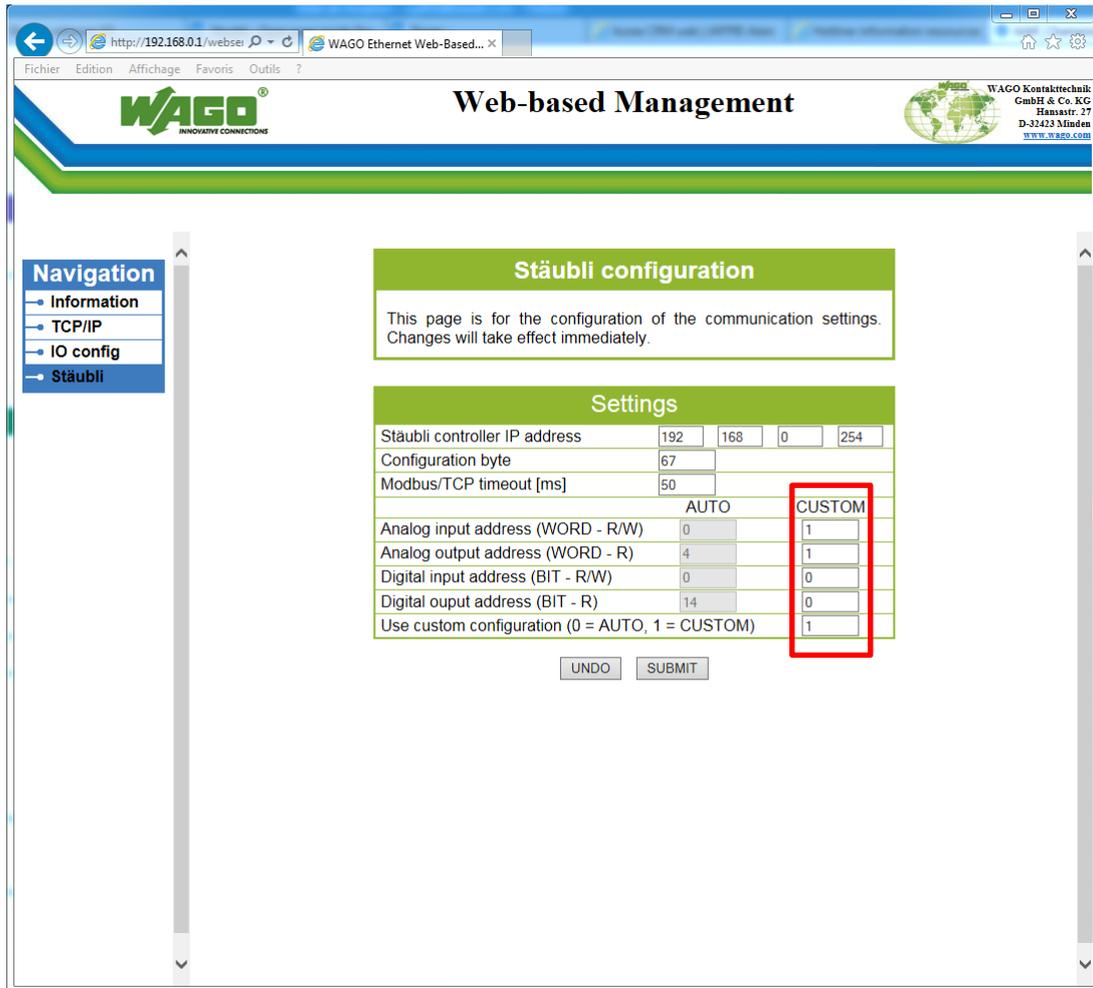
Below a sample SRS configuration for such client with 12 digital inputs, 8 digital outputs, 2 analog inputs and 4 analog outputs.



Below, corresponding WAGO coupler configuration where analog input and output must be shifted by the amount of word used for the bits and thus use a custom configuration.

Login: admin

Password: wago



7 Modbus client on CS9

Internally, all is managed as word but stored in 2 bytes.

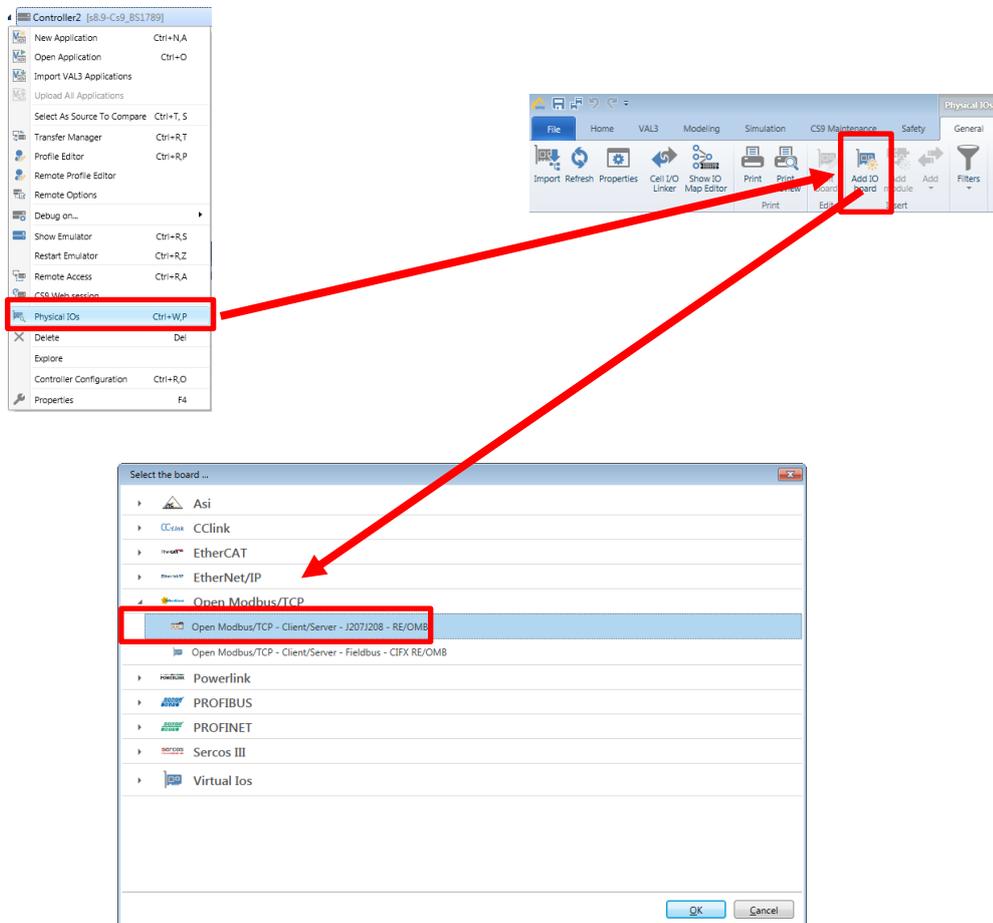
For data transmission, Modbus protocol specify that values must be encoded as big endian (Most Significant Byte first then Last Significant Byte).

On CS9 this also apply on coils for their internal storage, thus you will have a swap between first 8 coils and last 8 coils:

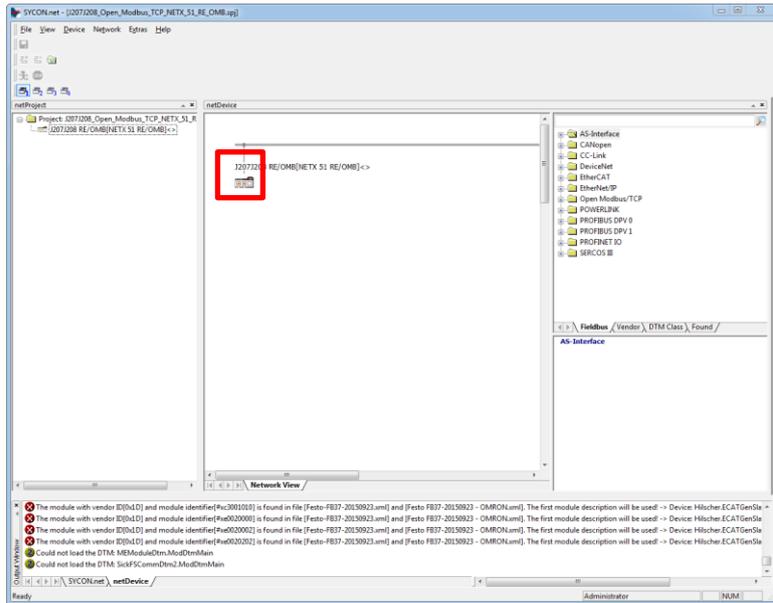
| Bit | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
|------|---|----|----|----|----|----|----|----|---|---|----|----|----|----|----|----|
| Coil | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |

If you use “Data swap”, coils (digital IOs) will be back in order but the 2 bytes used of registers (analog IOs) will be swapped also and thus may give erroneous value.

In SRS, select the controller in the cell explorer, make a right click on it and select “Physical IOs”, “Add IO board”, “Open Modbus/TCP – Client/Server – J207/J208 – RE/OMB”

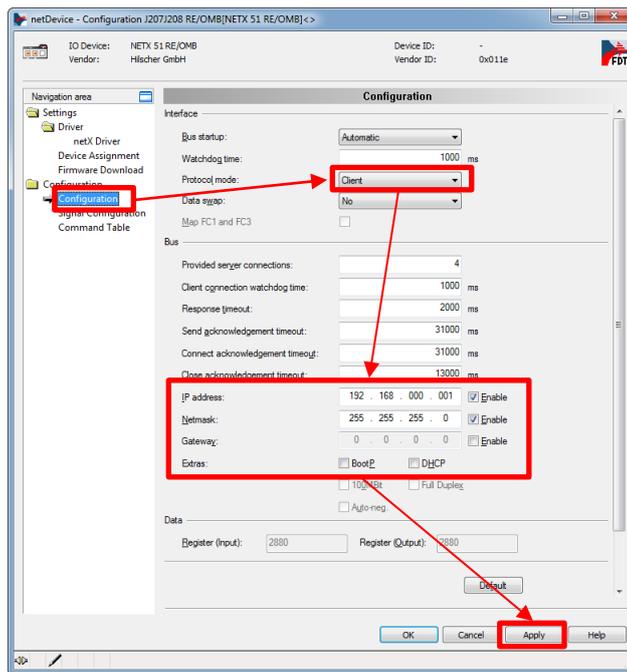


This open SYCON.net. Double click on J207/J208



Select "Configuration" branch, select "Client".

Uncheck "DHCP", enable and set "IP address" and "Netmask". Here, you specify the client address.
"Apply".

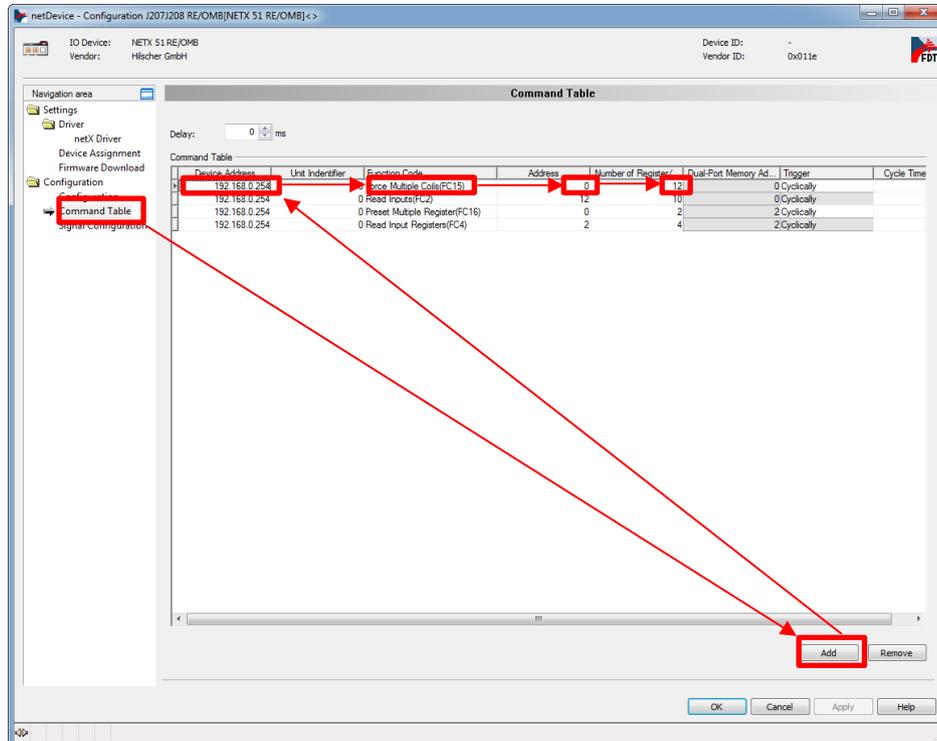


7 - Modbus client on CS9

Select "Command table" branch.

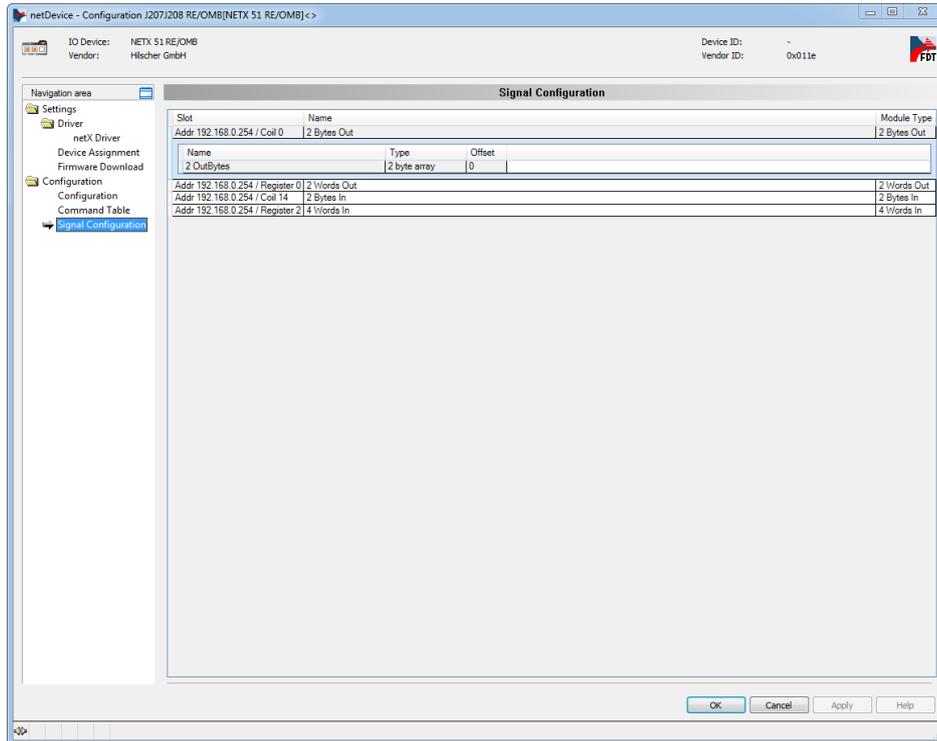
Add as many device as needed

For each device, you specify the server IP address in "Device Address", Select the proper "Function code", specify the start "Address" and the "Number of Register".



Select "Signal configuration" branch.

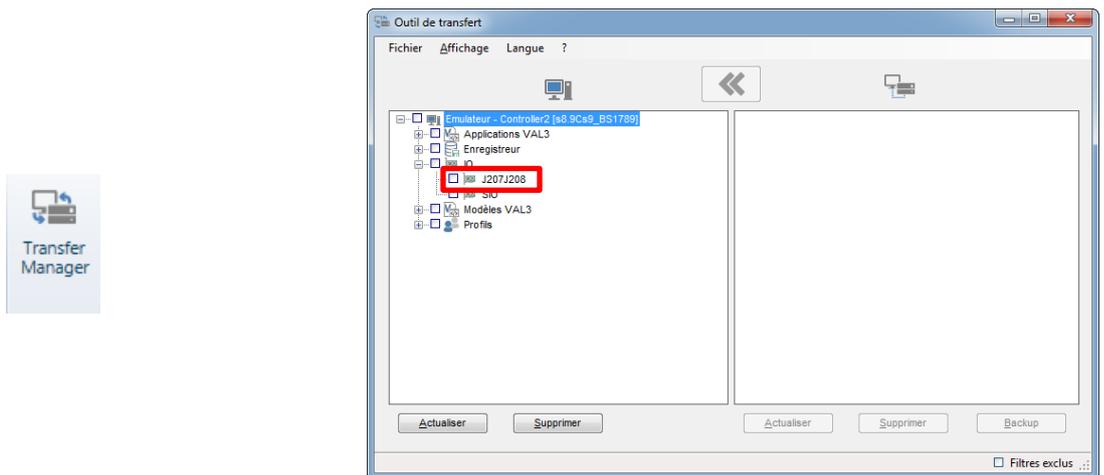
Split "Bytes Out", "Words Out", "Bytes In", "Words In" as defined in the exchange table.



When finished, press "OK" then "File", "Save" and close SYCON.

With "Transfer manager", send the "J207/J208" configuration to the controller.

Reboot the controller in order to take into account the new configuration.

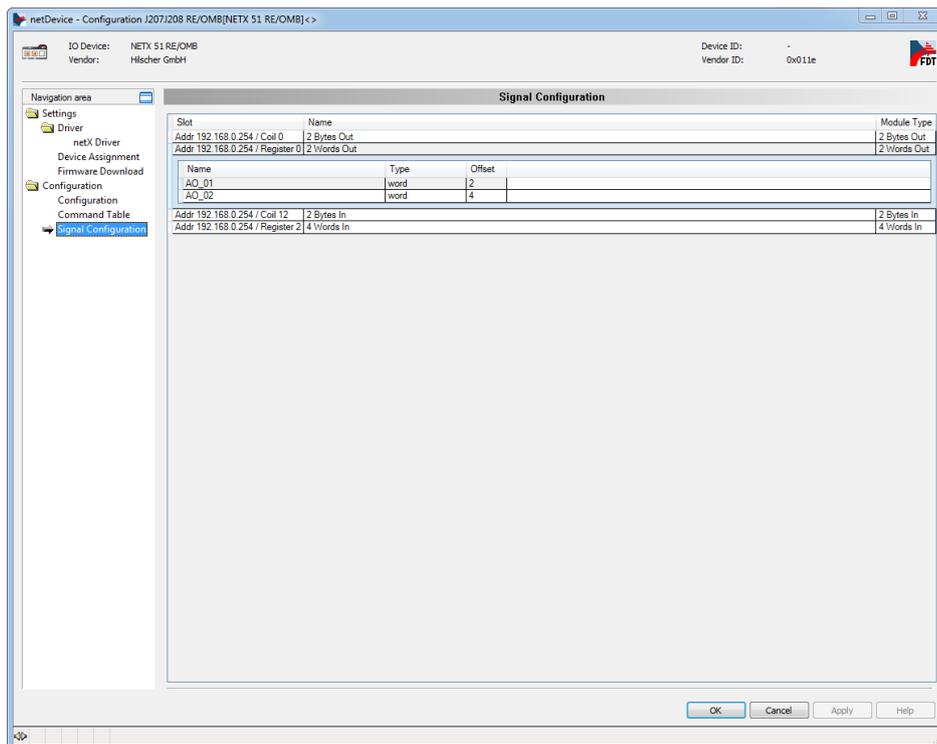
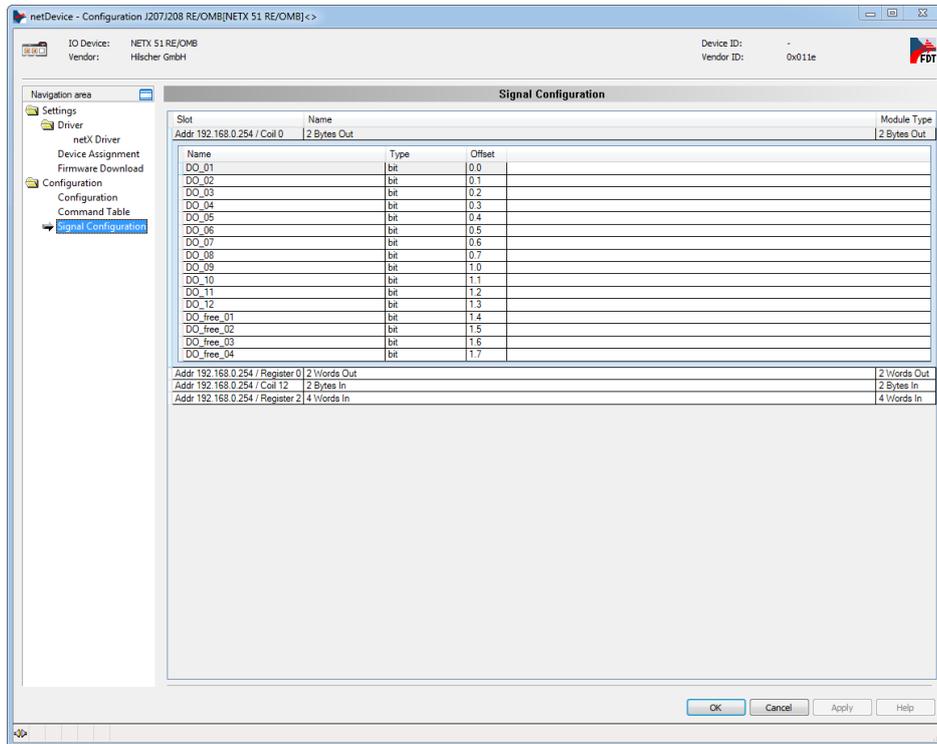


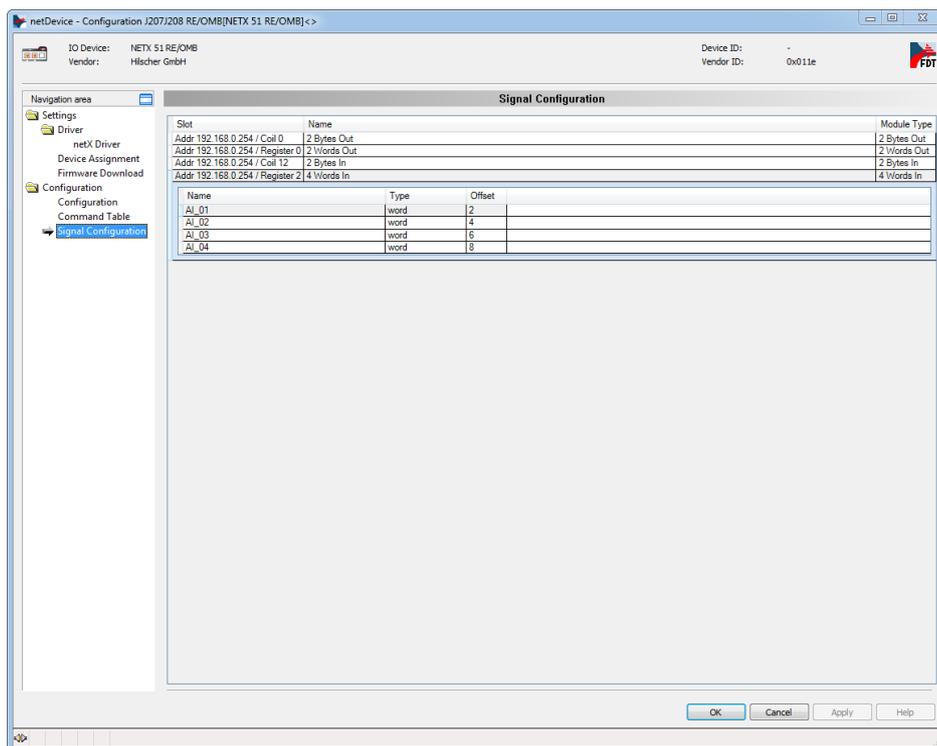
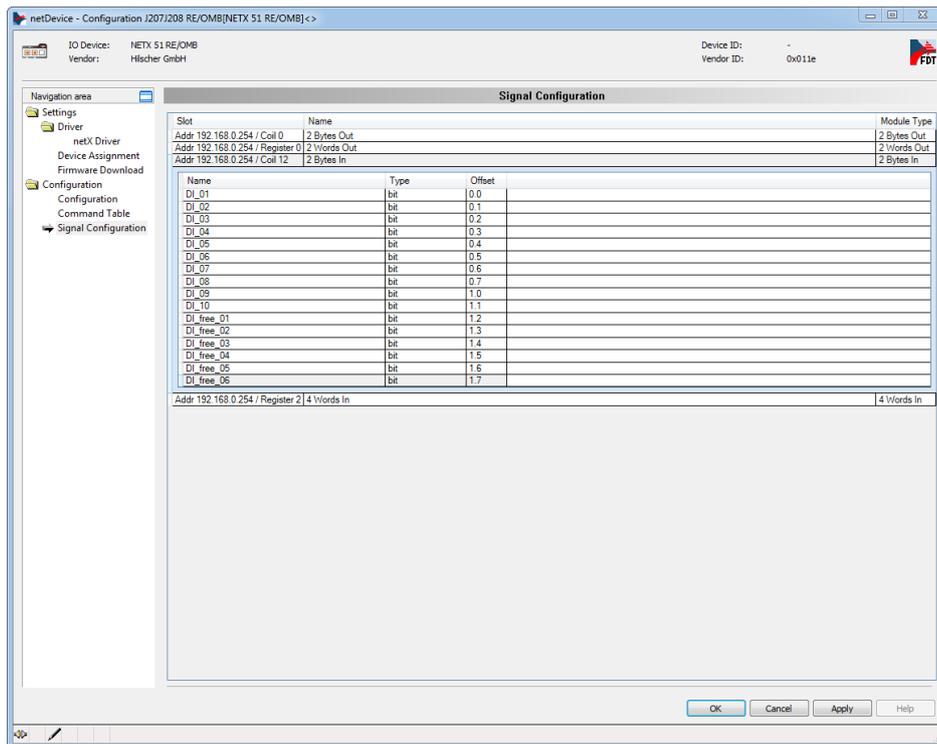
7.1 Example with a CS9 configured as a client connected to a CS8C as server

We have:

- 12 digital outputs, FC15, start at address 0, quantity 12
- 10 digital inputs, FC2, start at address 12 (the 12 digital outputs), quantity 10
- 2 analog outputs, FC16, start at address 0, quantity 2
- 4 analog inputs, FC4, start at address 2 (the 2 analog outputs), quantity 4

| CS9 client (master) | | | | CS8C, server (slave) | | | |
|---------------------|------|-----|-------------|----------------------|-----|------|----------------|
| | Word | Bit | Output name | Input name | Bit | Word | |
| Digital output | 1 | 1 | DO_01 | DI_01 | 9 | 1 | Digital input |
| | | 2 | DO_02 | DI_02 | 10 | | |
| | | 3 | DO_03 | DI_03 | 11 | | |
| | | 4 | DO_04 | DI_04 | 12 | | |
| | | 5 | DO_05 | DI_05 | 13 | | |
| | | 6 | DO_06 | DI_06 | 14 | | |
| | | 7 | DO_07 | DI_07 | 15 | | |
| | | 8 | DO_08 | DI_08 | 16 | | |
| | | 9 | DO_09 | DI_09 | 1 | | |
| | | 10 | DO_10 | DI_10 | 2 | | |
| | | 11 | DO_11 | DI_11 | 3 | | |
| | | 12 | DO_12 | DI_12 | 4 | | |
| | | 13 | DO_free_01 | DI_free_01 | 5 | | |
| | | 14 | DO_free_02 | DI_free_02 | 6 | | |
| | | 15 | DO_free_03 | DI_free_03 | 7 | | |
| | | 16 | DO_free_04 | DI_free_04 | 8 | | |
| Digital input | 1 | 1 | DI_01 | DO_01 | 9 | 1 | Digital output |
| | | 2 | DI_02 | DO_02 | 10 | | |
| | | 3 | DI_03 | DO_03 | 11 | | |
| | | 4 | DI_04 | DO_04 | 12 | | |
| | | 5 | DI_05 | DO_05 | 13 | | |
| | | 6 | DI_06 | DO_06 | 14 | | |
| | | 7 | DI_07 | DO_07 | 15 | | |
| | | 8 | DI_08 | DO_08 | 16 | | |
| | | 9 | DI_09 | DO_09 | 1 | | |
| | | 10 | DI_10 | DO_10 | 2 | | |
| | | 11 | DI_free_01 | DO_free_01 | 3 | | |
| | | 12 | DI_free_02 | DO_free_02 | 4 | | |
| | | 13 | DI_free_03 | DO_free_03 | 5 | | |
| | | 14 | DI_free_04 | DO_free_04 | 6 | | |
| | | 15 | DI_free_05 | DO_free_05 | 7 | | |
| | | 16 | DI_free_06 | DO_free_06 | 8 | | |
| Analog output | 2 | | AO_01 | AI_01 | | 2 | Analog input |
| | 3 | | AO_02 | AI_02 | | 3 | |
| Analog input | 2 | | AI_01 | AO_01 | | 2 | Analog output |
| | 3 | | AI_02 | AO_02 | | 3 | |
| | 4 | | AI_03 | AO_03 | | 4 | |
| | 5 | | AI_04 | AO_04 | | 5 | |





8 Appendix

8.1 Modbus function code

Extract from Modbus specification (<http://www.modbus.org/specs.php>)

| Data type | Mode | Function name | Function code (FC) |
|-----------------------|-------------------------------|--------------------------|--------------------|
| Bit | Digital input (read only) | Read Discrete Inputs | 2 |
| | Digital output (read / write) | Read Coils | 1 |
| | | Write Single Coil | 5 |
| | | Write Multiple Coils | 15 |
| Word (16 bits) | Analog input (read only) | Read Input Registers | 4 |
| | Analog output (read / write) | Read Holding Registers | 3 |
| | | Write Single Register | 6 |
| | | Write Multiple registers | 16 |